



# On the road to the Preliminary Design Review of the MAORY adaptive optics module for E-ELT

## MAORY Road Crew:

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**Speaker: Emiliano Diolaiti, INAF**



# Project overview

## MAORY

- First light instrument for European ELT
  - HARMONI, MAORY, METIS, MICADO
- Adaptive optics module

## Client instruments

- MICADO, near infrared camera and spectrograph
  - 0.8-2.5  $\mu\text{m}$ , 53x53 arcsec<sup>2</sup>
- 2<sup>nd</sup> instrument as yet undefined

## Adaptive optics modes

- MCAO
- SCAO → joint development MICADO-MAORY
- Other
  - seeing-enhancer, calibration, engineering, ...

## Project status

- Phase B is in progress
- Kick-off February 2<sup>nd</sup>, 2016
- Preliminary Design Review planned Q1-2018



# Wavefront control on E-ELT

## E-ELT

- Adaptive telescope
- 5 mirror design (including adaptive M4 and tip-tilt M5)

## Blind control layer embedded in telescope

- Maintains M1 figure
- Controls position of M2, M3, M4 at slow rate

## Active optics

- Compensates quasi-static aberrations in the telescope

## Adaptive optics

- Compensates fast aberrations (atmospheric turbulence, wind action on telescope, etc.)
- Relies on distributed resources in the telescope and in MAORY



# MCAO architecture overview / 1

## Wavefront compensation

- Telescopes's adaptive mirror M4
  - Projected actuator spacing 0.5 m
- Telescope's tip-tilt mirror M5
- 1 or 2 post-focal DMs within MAORY
  - Projected actuator spacing 1.5-2 m



# MCAO architecture overview / 2

## Wavefront sensing

- 6 sodium LGS wavefront sensors within MAORY
  - 80x80 subapertures, 500 fps
  - Fixed w.r.t telescope pupil,  $\varnothing 90$  arcsec on sky
- (Up to) 3 NGS wavefront sensors within MAORY
  - NGS patrol field of view  $\varnothing 180$ -200 arcsec
  - Low-order channel, 1.5-1.8  $\mu\text{m}$ , 2x2 subap, Tip-Tilt Focus & Astigmatism, 500 fps (or lower)
  - Reference/truth channel, 0.6-0.9  $\mu\text{m}$ , 10x10 subap, 0.1-1 fps
- (Up to) 3 NGS wavefront sensors in the telescope
  - Active optics loop
  - Tip-tilt compensation in cascade control mode
    - Alternate mode: sequential handover
  - NGS patrol field of view  $\varnothing 10$  arcmin



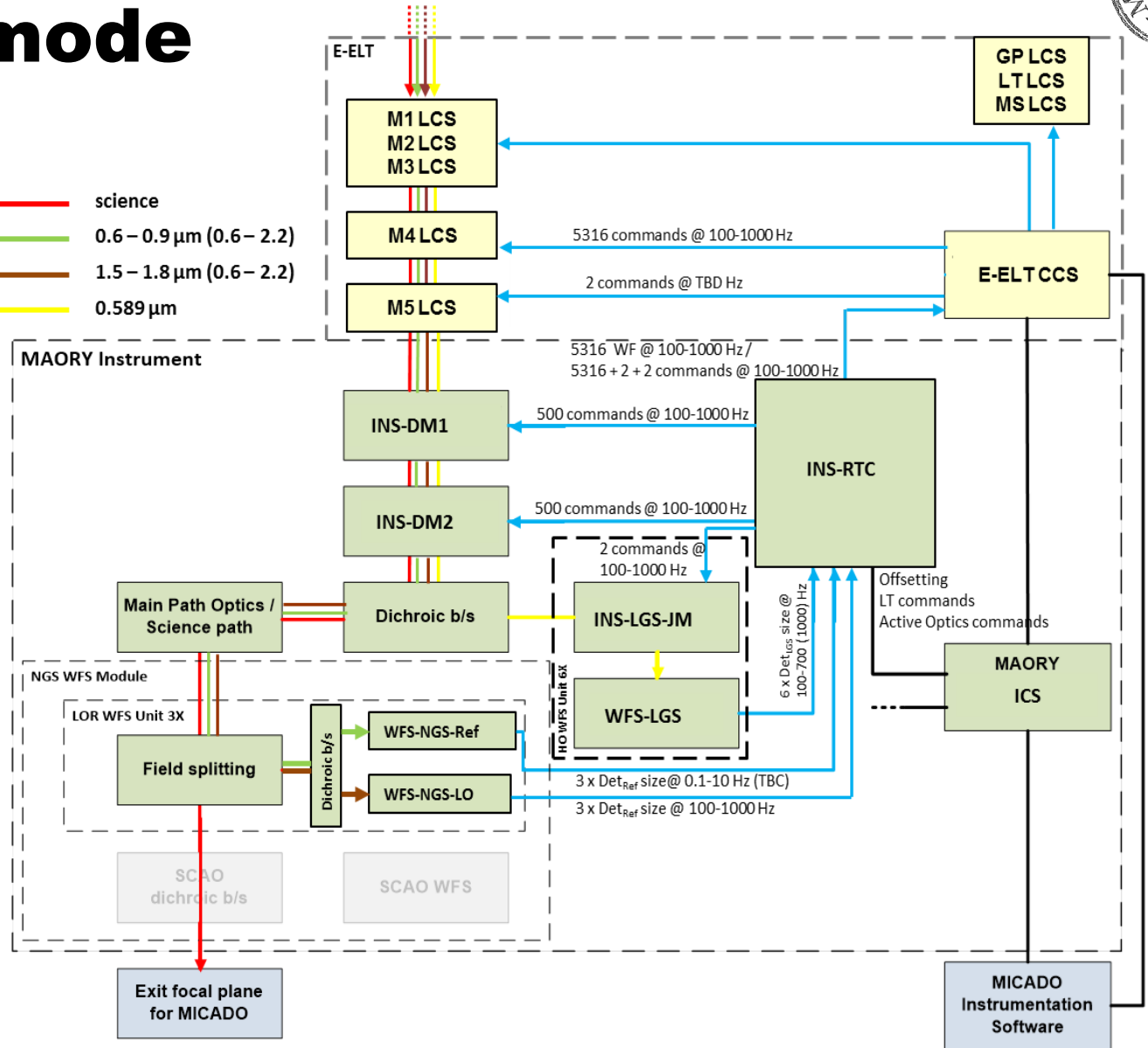
# MCAO mode

Telescope

MAORY

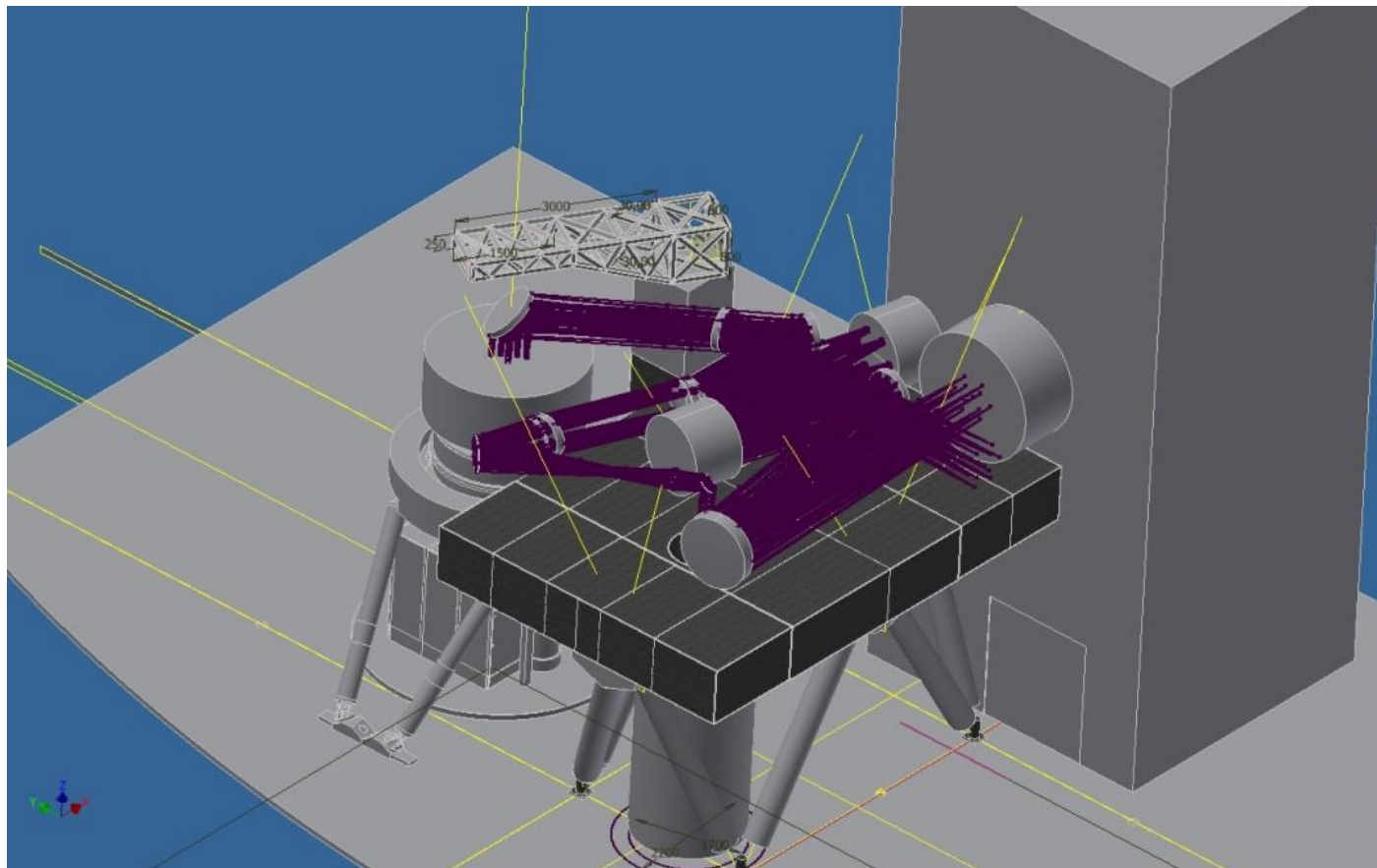
MICADO

- science
- 0.6 – 0.9  $\mu\text{m}$  (0.6 – 2.2)
- 1.5 – 1.8  $\mu\text{m}$  (0.6 – 2.2)
- 0.589  $\mu\text{m}$





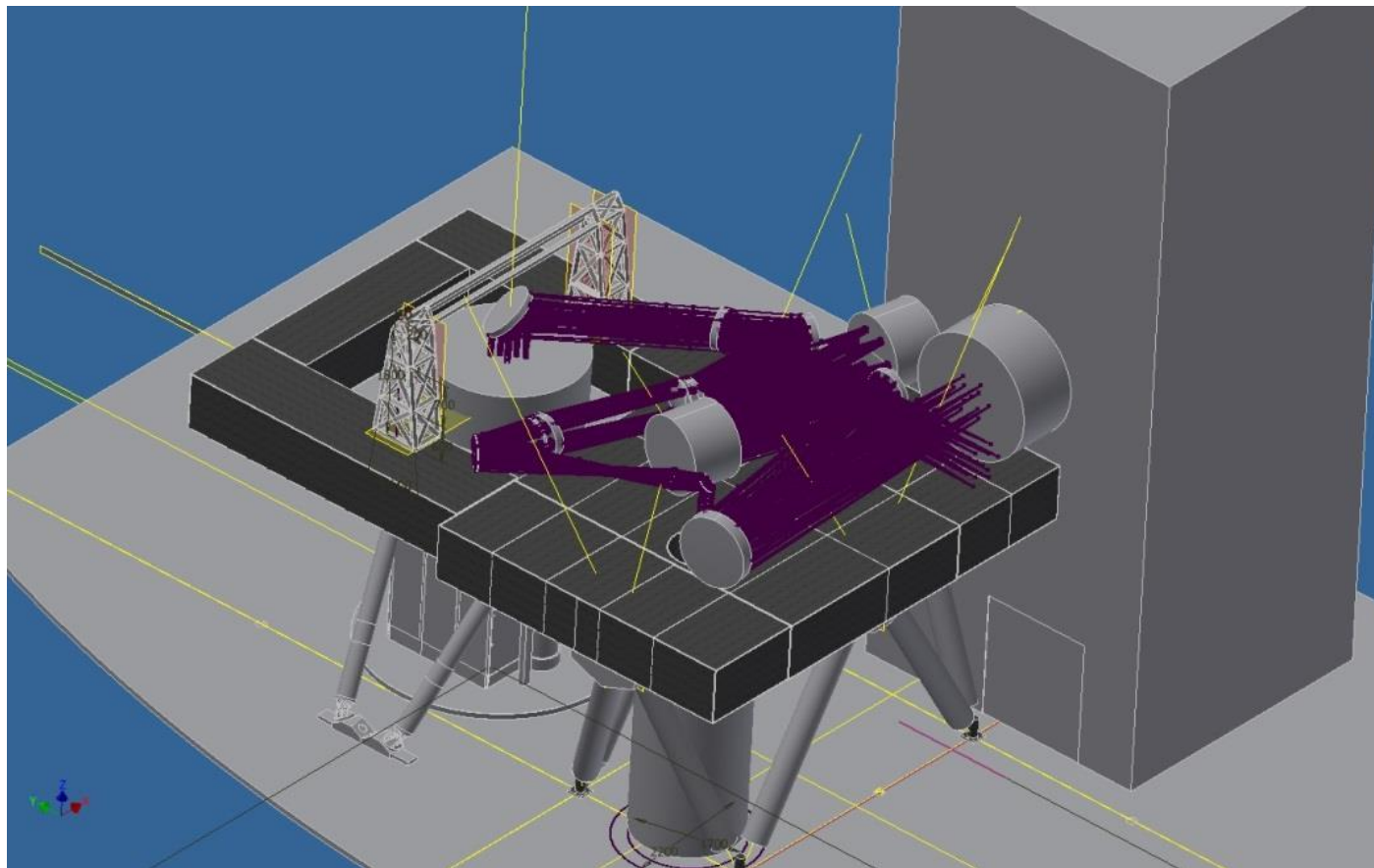
# Main structure / 1



M11 “swing arm” concept



# Main structure / 2

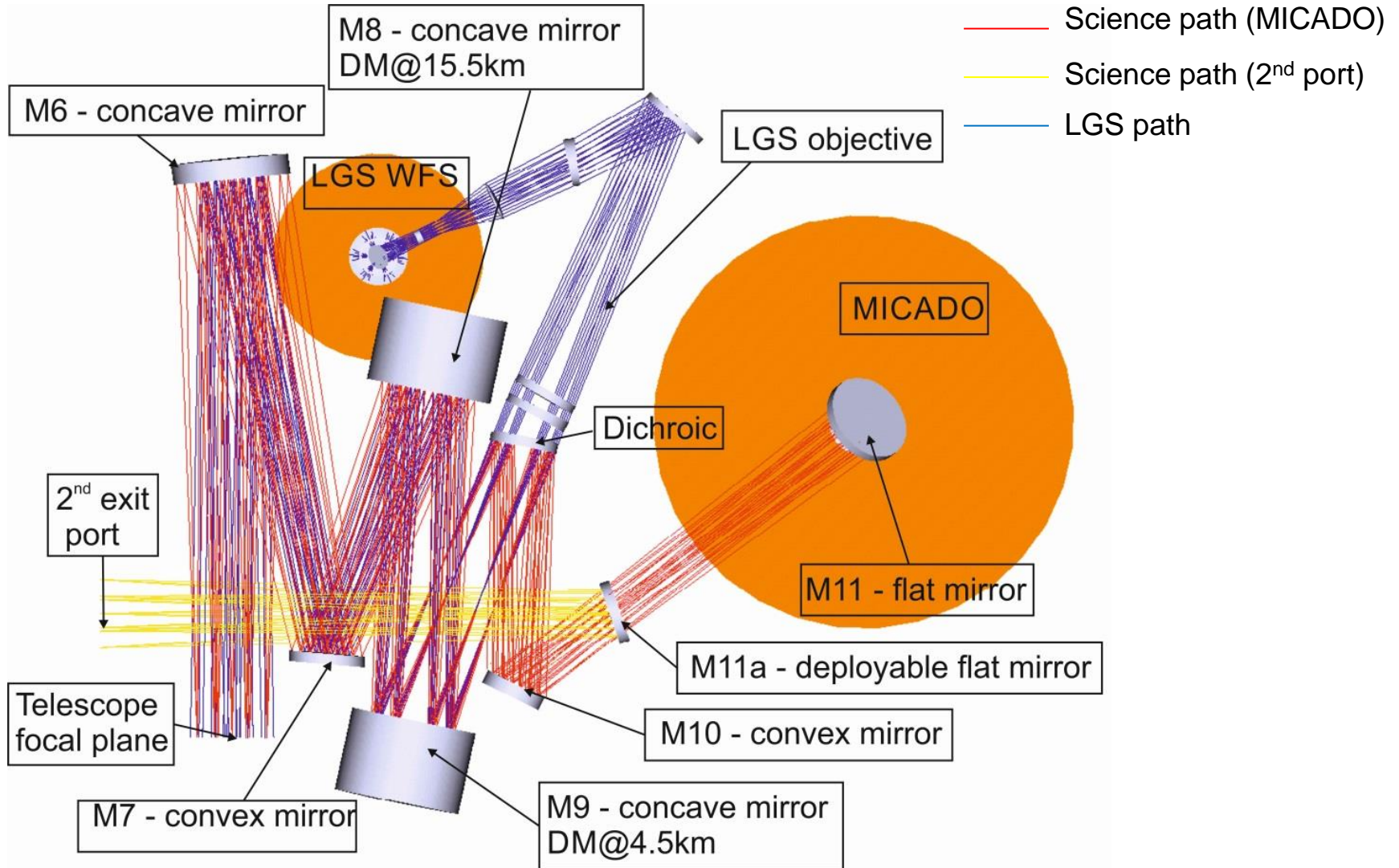


M11 "bridge" concept



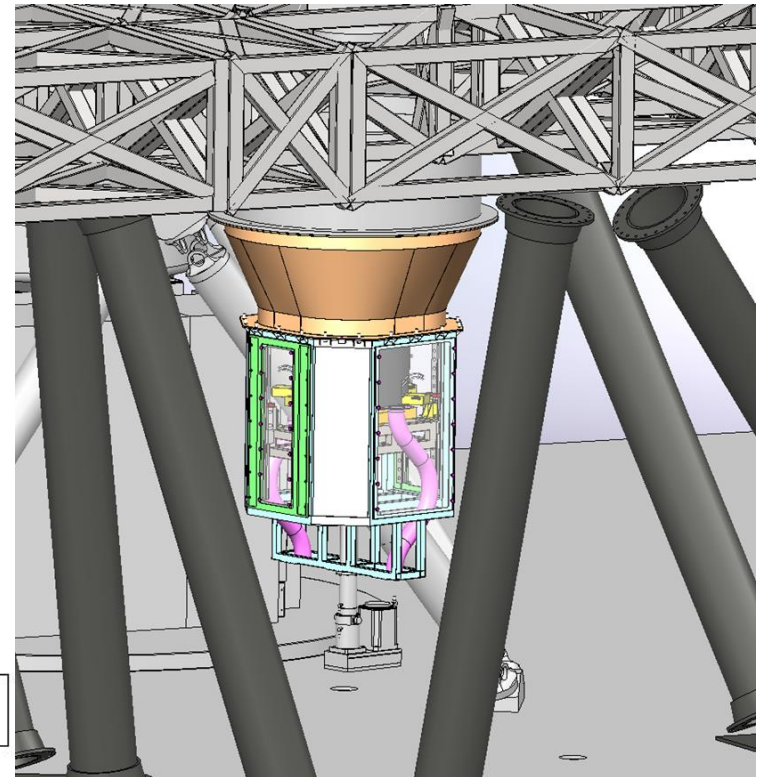
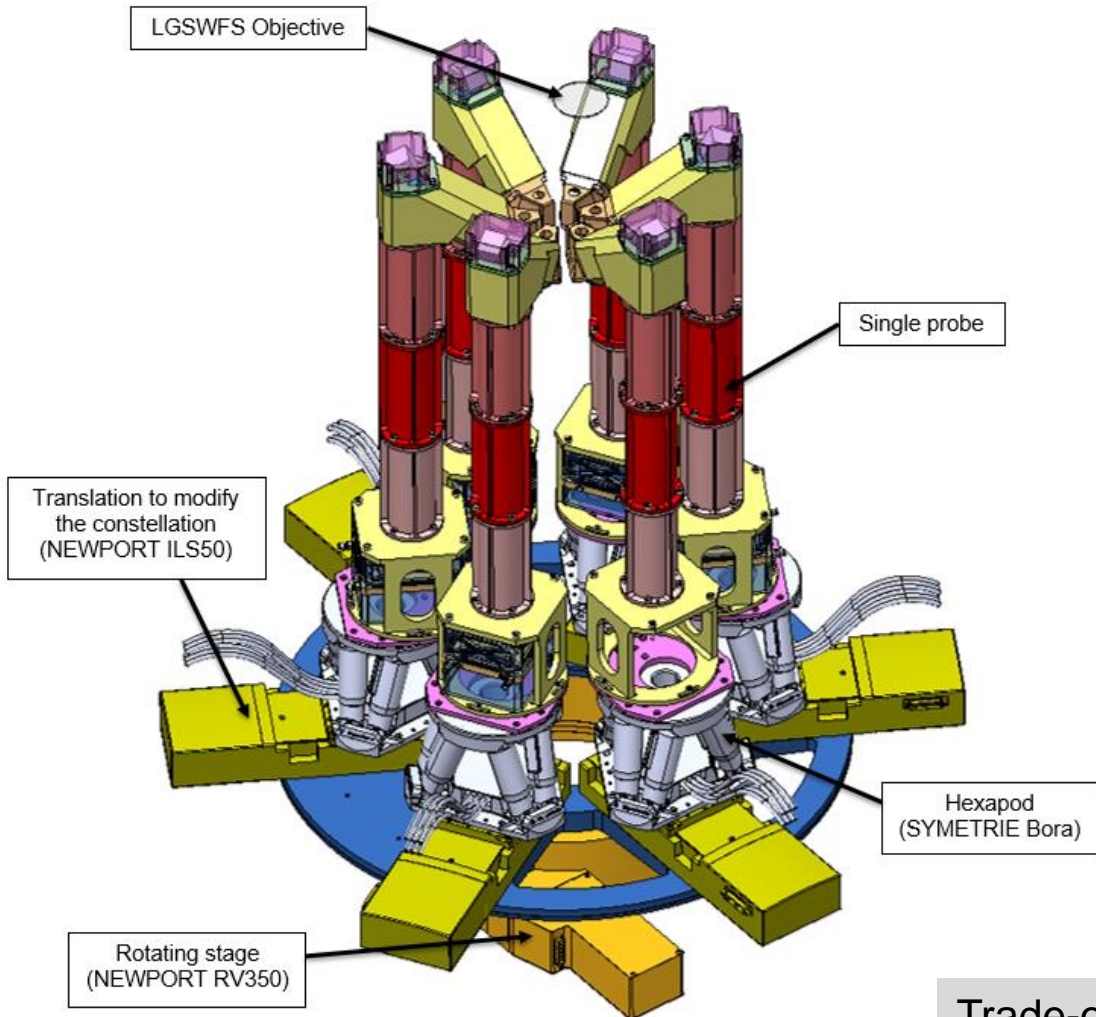


# Optical relay





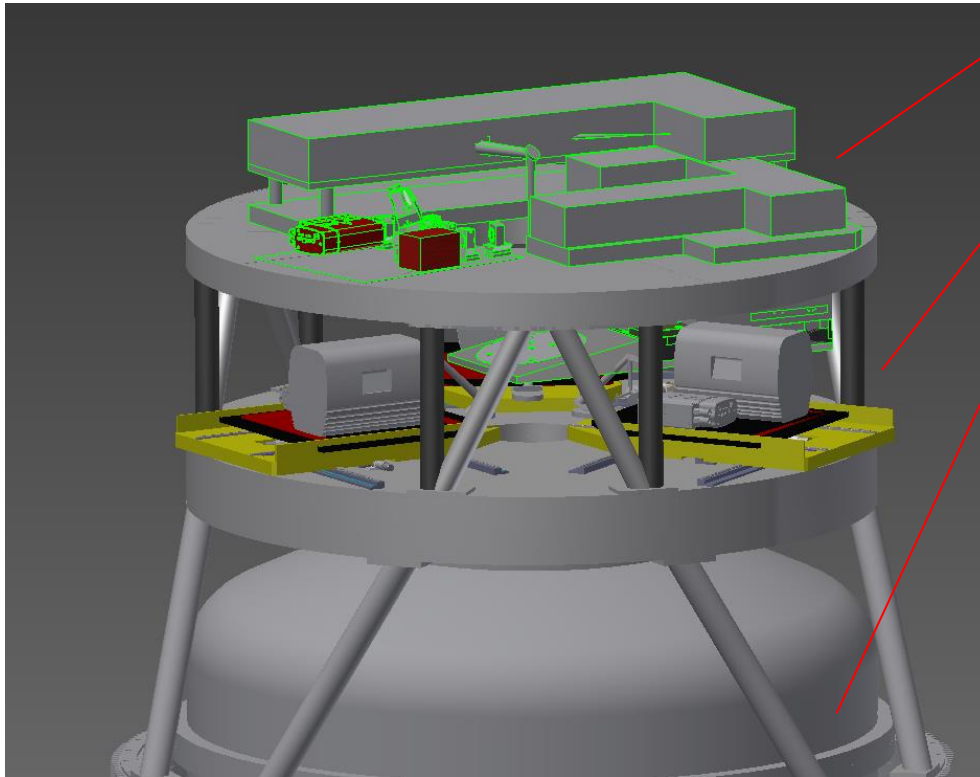
# LGS wavefront sensor



Trade-off FoV vs. LGS spot sampling



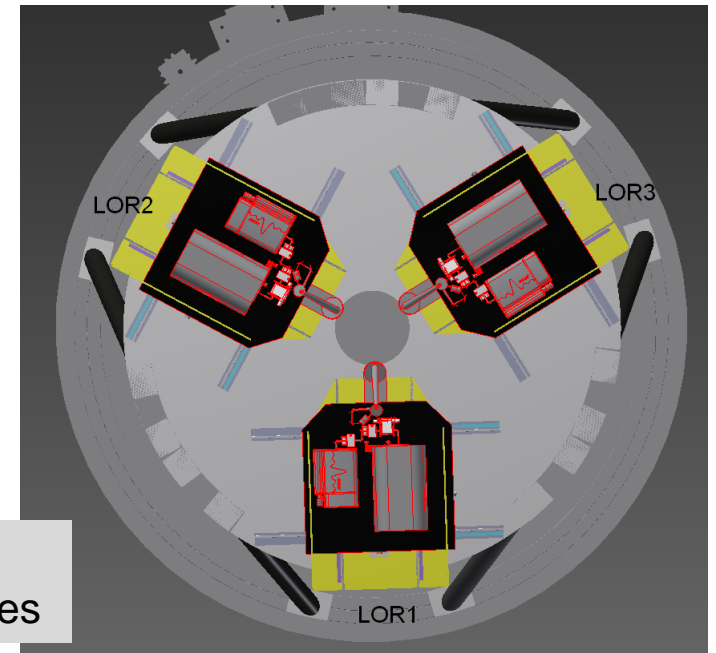
# NGS wavefront sensor module



SCAO plate (SCAO mode)

LOR plate (MCAO mode)

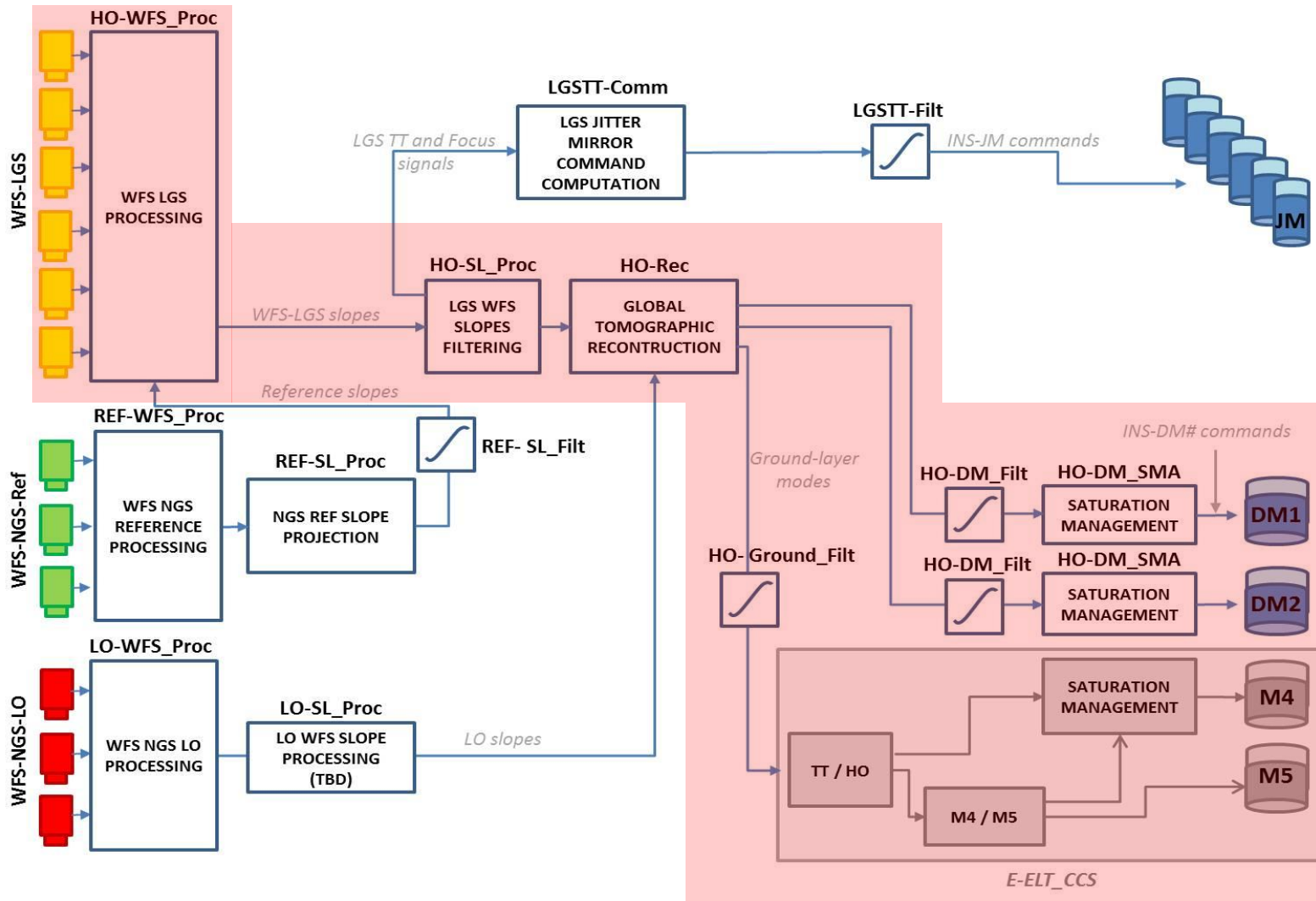
MICADO cryostat



Relative astrometric accuracy system requirement  
→ 2 mas differential positioning error among NGS probes



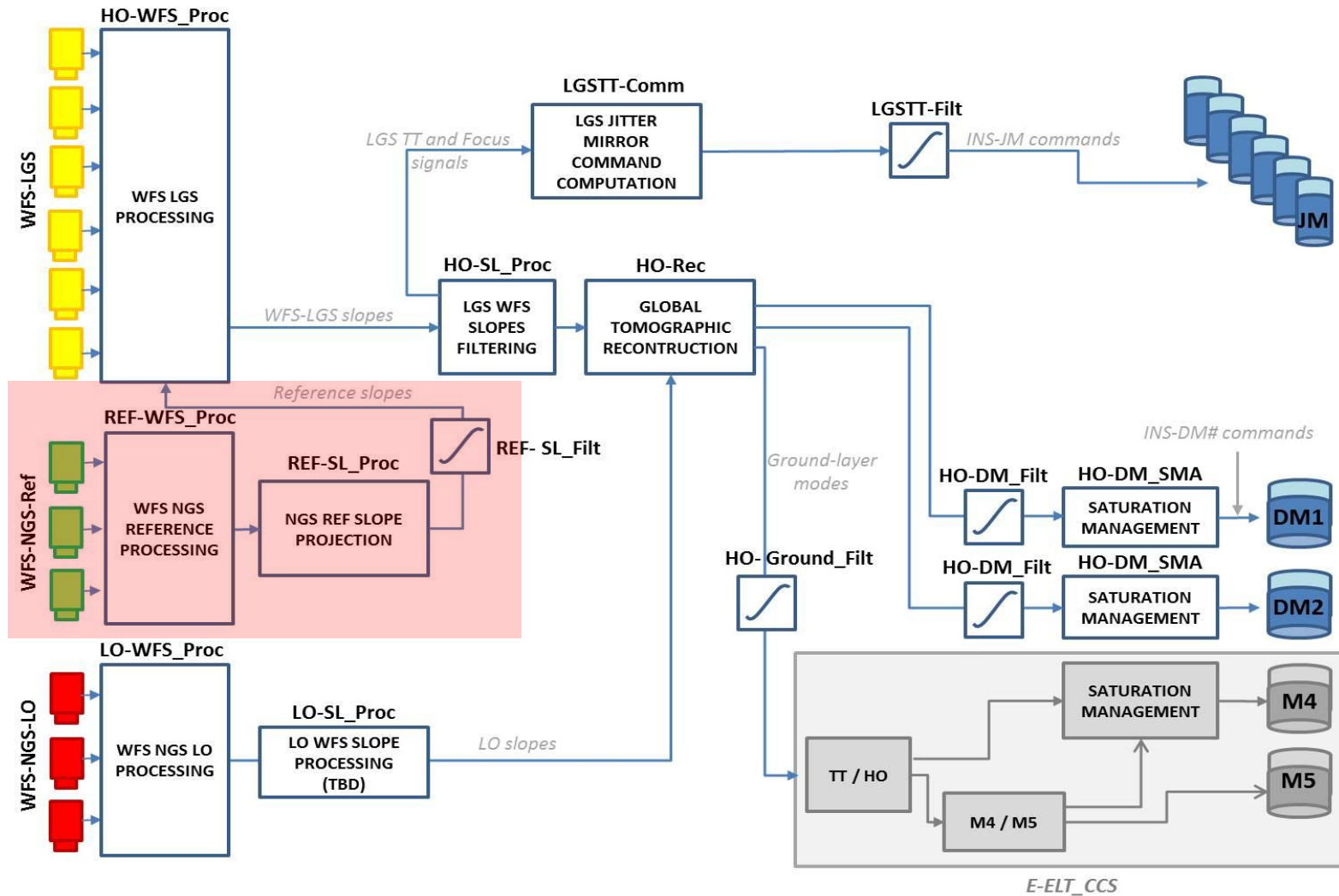
# RTC LGS high-order control loop





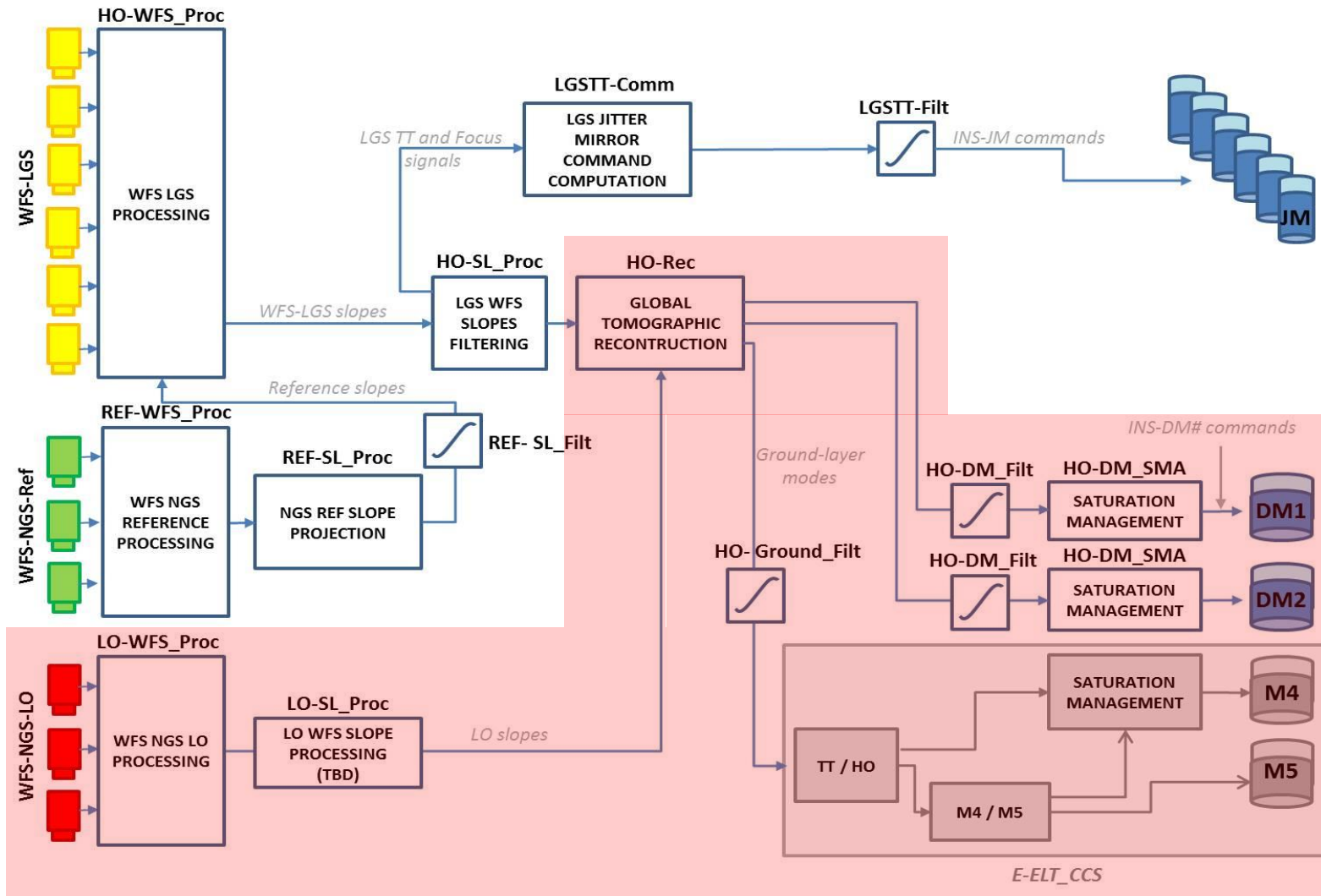


# RTC NGS reference control loop





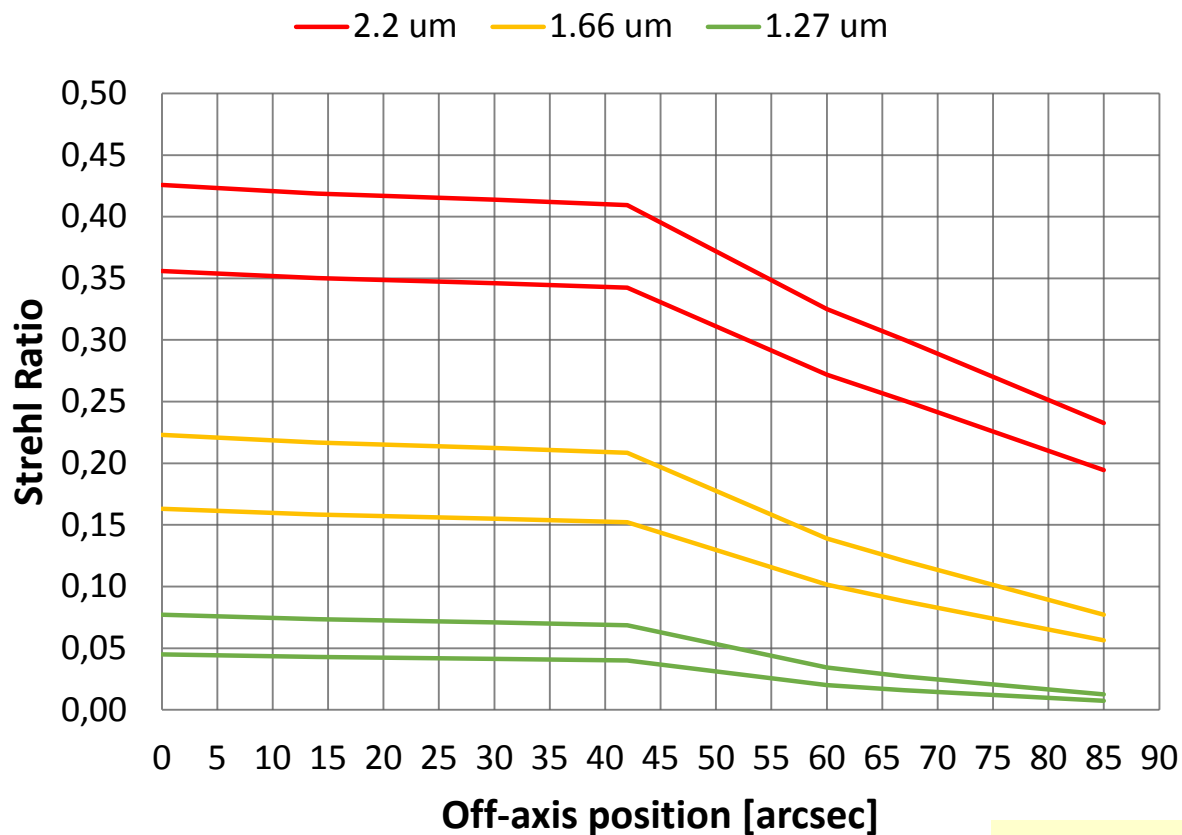
# RTC NGS low-order control loop





# MCAO performance

Median seeing - Zenith - 50% sky coverage @GP



Sub-system	WFE nm
E-ELT	145
MCAO architecture	217
Post-focal relay	102
NGS WFS	99
LGS WFS	98
RTC	163
Contingency	48
<b>Total</b>	<b>356</b>

Gain with 2<sup>nd</sup> post-focal DMs

- Sky coverage
- Robustness to Cn2 profile variations



# Related talks/posters

**Mauro Patti** - Exploring MAORY performances through tolerance analysis [P1012]

**Carmelo Arcidiacono** - Status of the MAORY numerical simulation tool [P1053]

**Gabriele Rodeghiero** - Towards an overall astrometric error budget with MICADO-MCAO

**Marco Bonaglia** - Design and status of the NGS WFS of MAORY [P2035]

**Matteo Lombini** - Laser Guide Star Objective of MAORY [P3009]

**Sylvain Oberti** - MAORY design trade-off study: tomography dimensioning