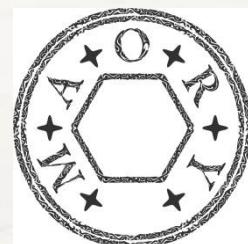
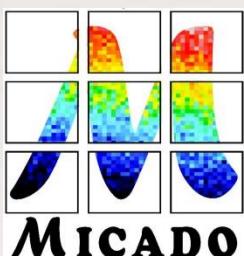


Towards an overall astrometric error budget with MICADO-MCAO

G. Rodeghiero, J.U. Pott, D. Massari, M. Fabricius, C. Arcidiacono,
F. Cortecchia, G. Fiorentino, M. Lombini

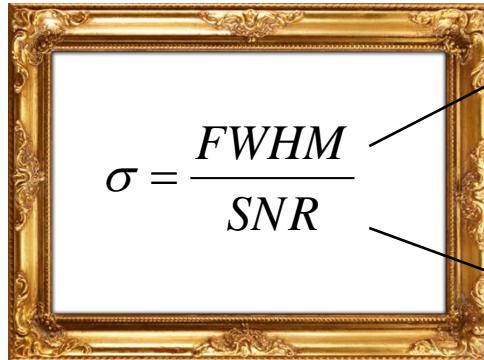
Overview

- Relative astrometry with ELTs
- E-ELT + MAORY + MICADO
- Monte Carlo simulations
- Distortion sensitivity analysis
- Worst offenders for astrometry
- Strategies for MICADO astrometry



Relative Astrometry with ELTs

VISION -> Relative astrometry at 50 μ as level



$$\sigma_{\text{ELTs}} \approx \sigma_{\text{8m class}} / 5$$



Distortion(t)



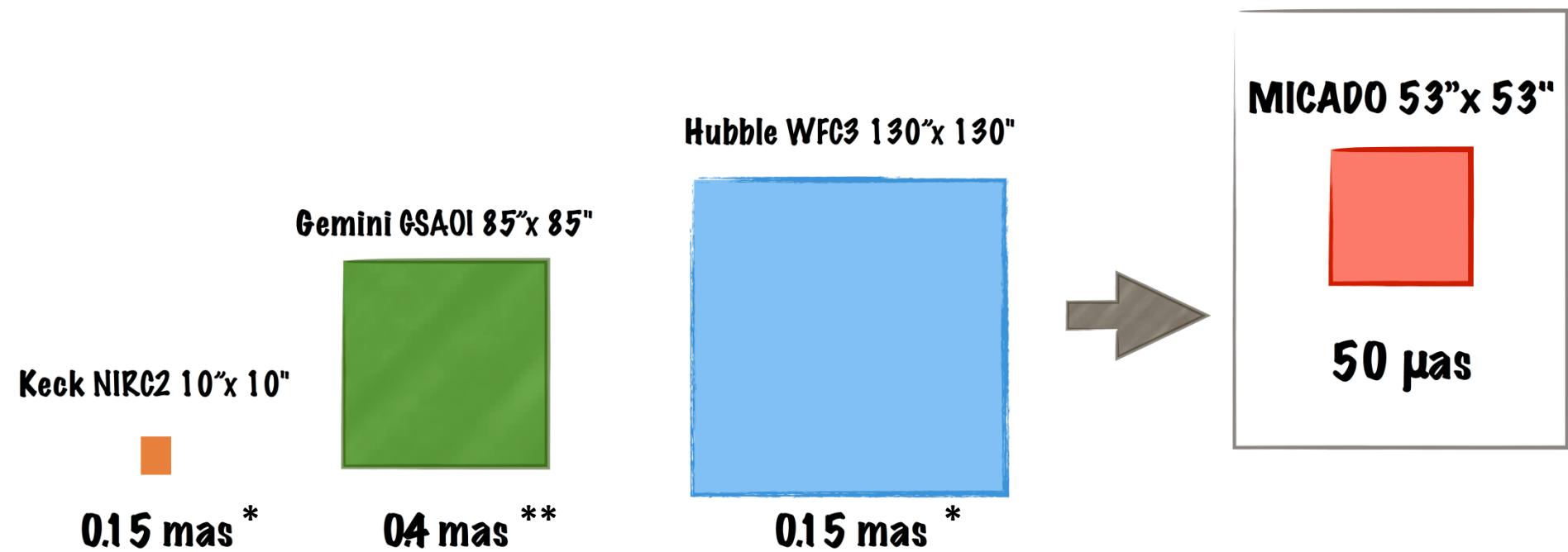
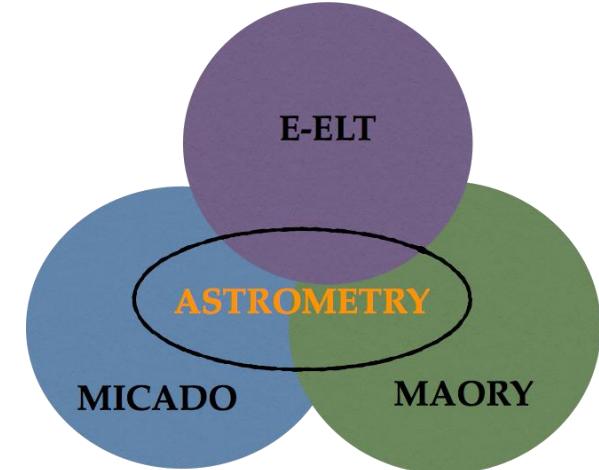
Telescopes 5 times bigger
smaller FWHM & higher SNR
BUT
stability issues



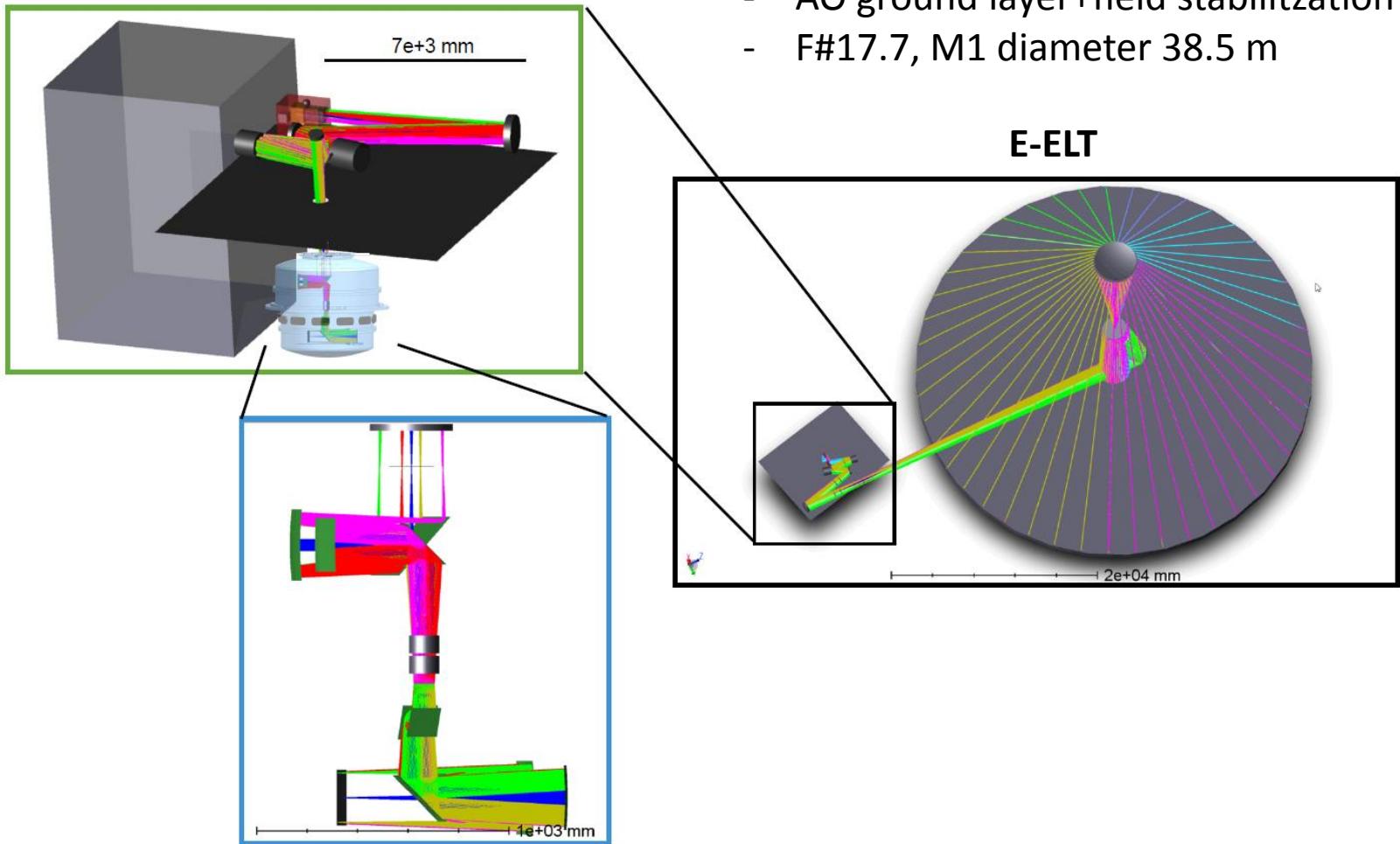
Relative Astrometry with ELTs

- Current instrument astrometry noise floor **0.15-0.4 mas**
- NIRC2 **SCAO**
- WFC3 Space
- GeMS **MCAO**

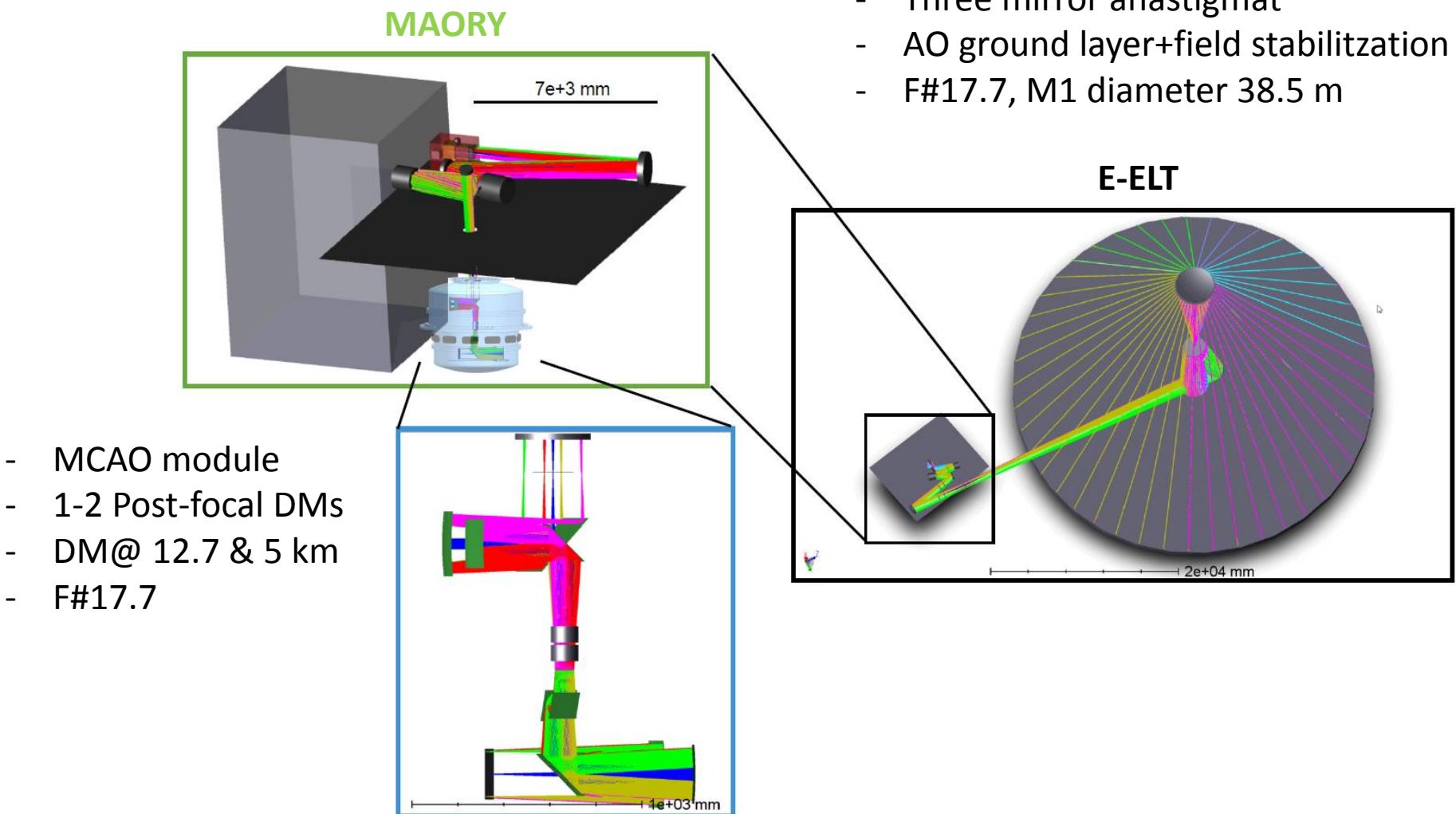
(*) Lu, 2014, (**) Neichel, 2014



E-ELT+MAORY+MICADO

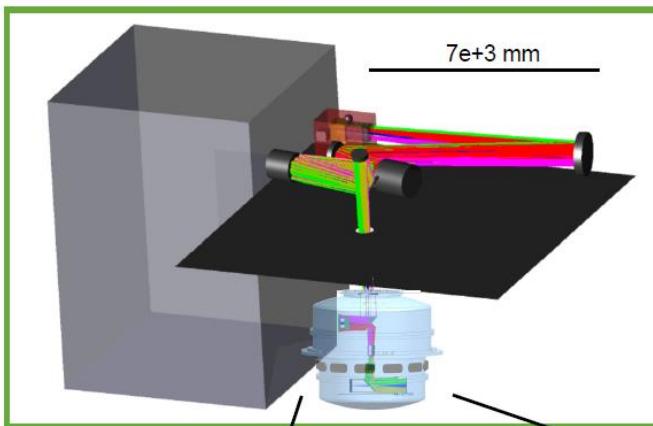


E-ELT+MAORY+MICADO



E-ELT+MAORY+MICADO

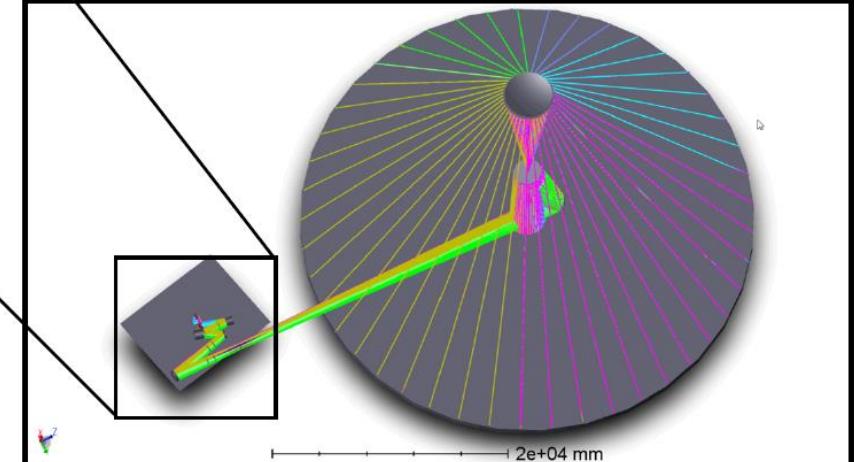
MAORY



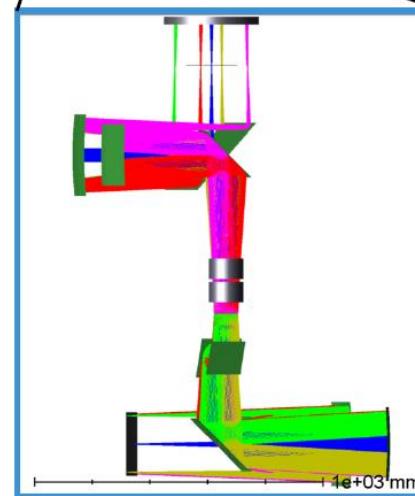
- MCAO module
- 1-2 Post-focal DMs
- DM@ 12.7 & 5 km
- F#17.7

- Three mirror anastigmat
- AO ground layer+field stabilization
- F#17.7, M1 diameter 38.5 m

E-ELT



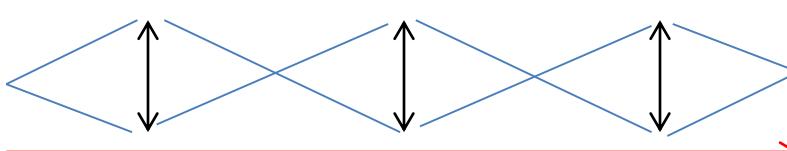
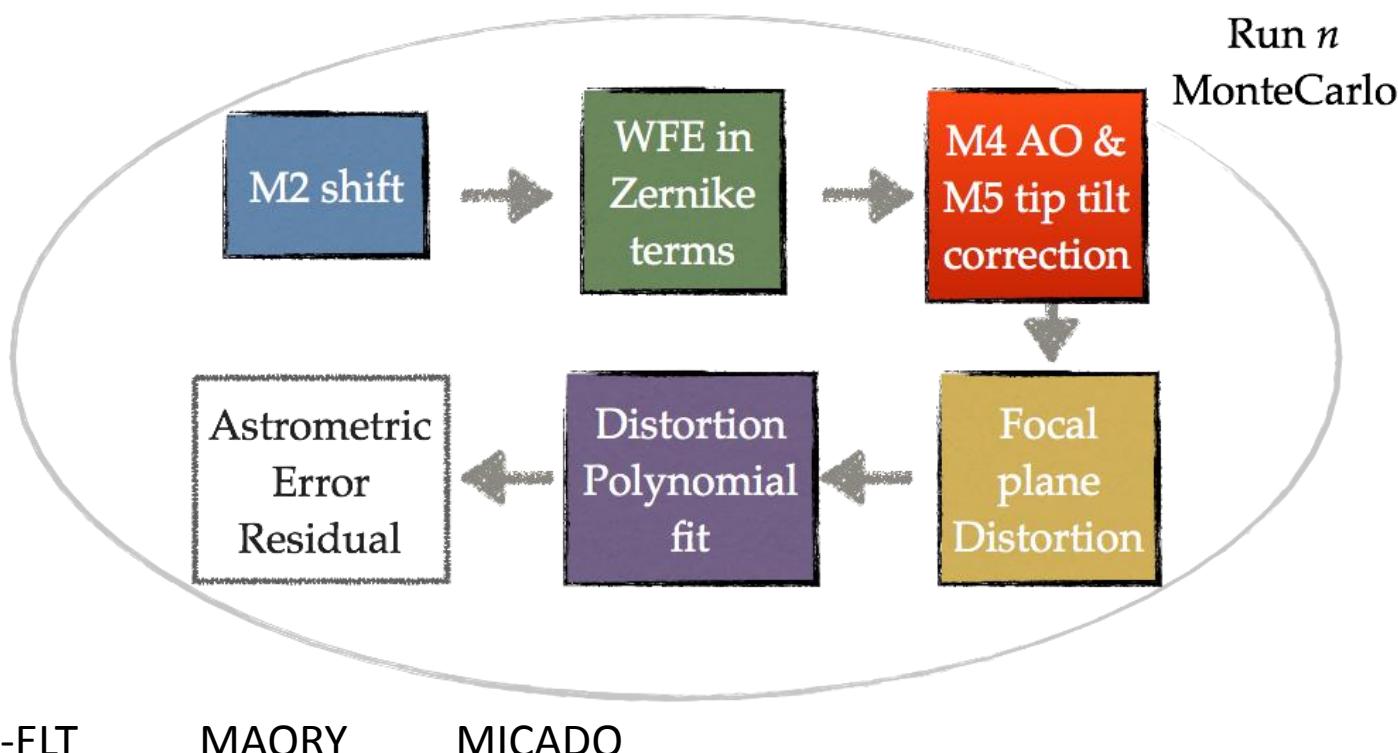
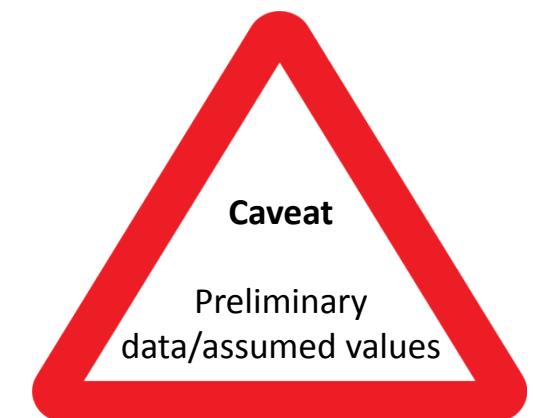
MICADO



- Camera & spectrometer
- 2 TMAs, only fixed mirrors
- Cryogenic, gravity invariant
- FoV 53", pixel scale 1.5-4.5 mas

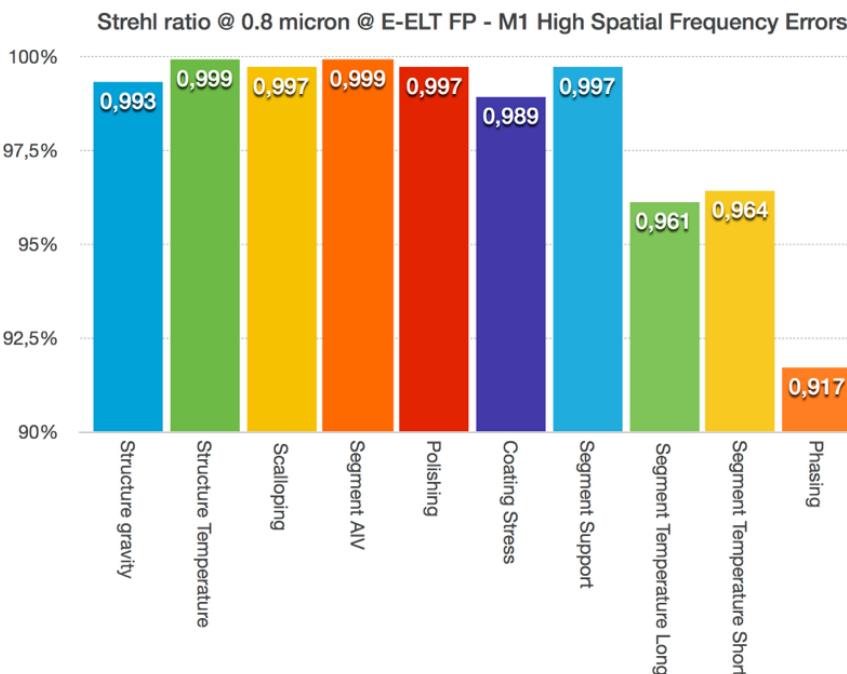
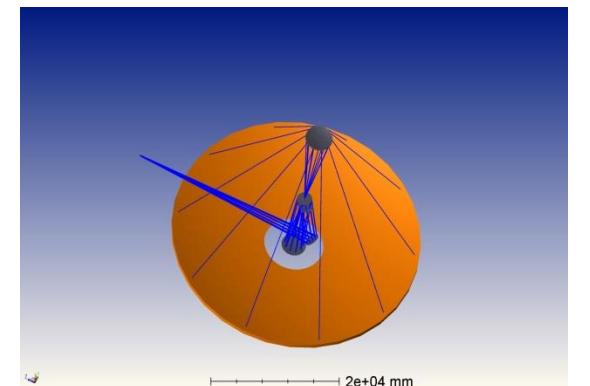
MC tolerances approach

- OpticStudio (Zemax) ZOS-API using Matlab

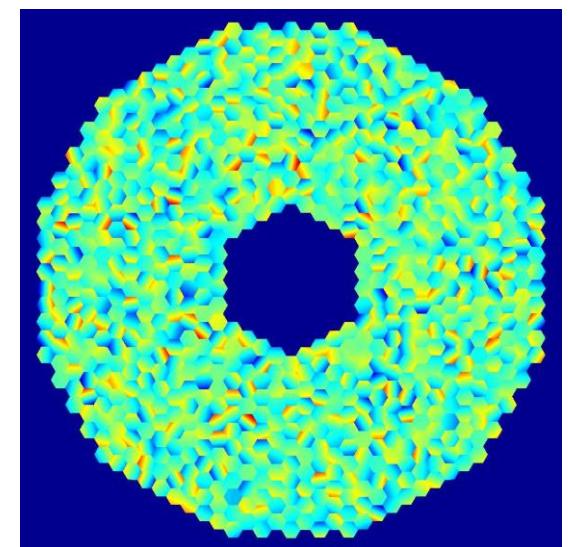


M1 Tolerances

- High spatial frequency errors
- Decrease of the Strehl ratio
- M1 at entrance pupil -> no differential distortion in FoV



Phasing errors



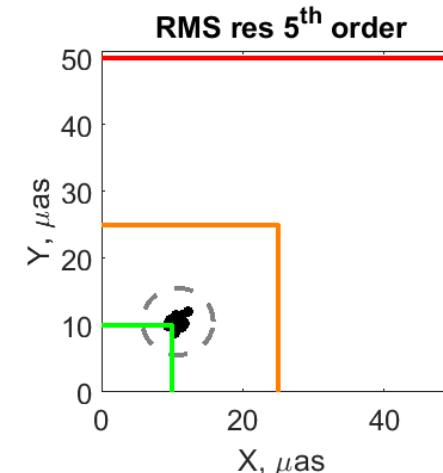
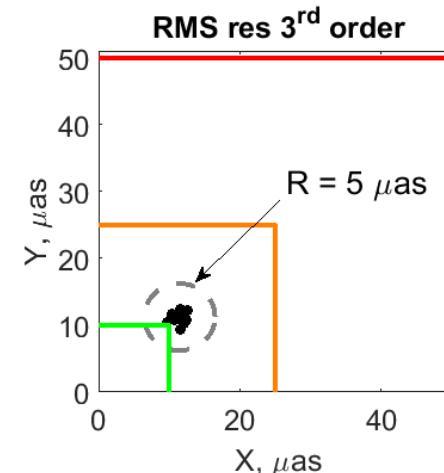
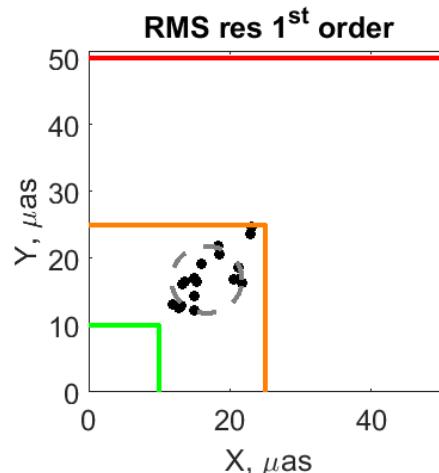
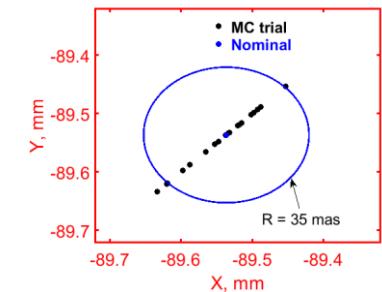
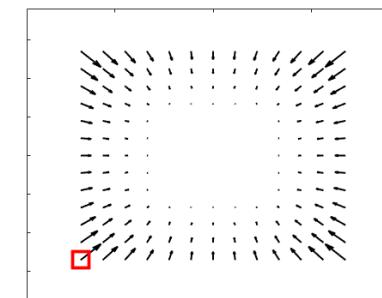
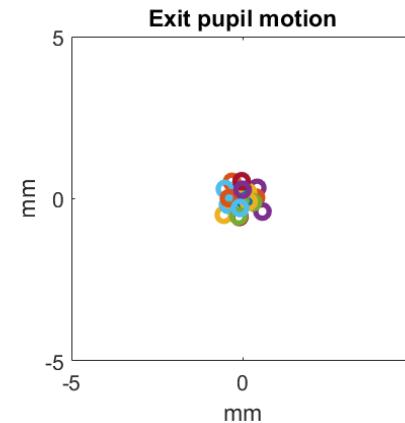
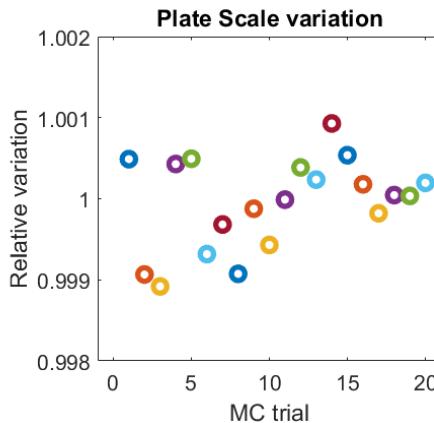
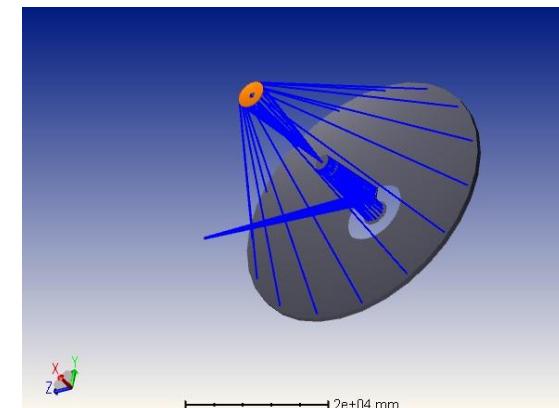
ESO dataset, Marchetti 2015

M2 Tolerances

$-0.1 \text{ mm} < dx, dy, dz < +0.1 \text{ mm}$

$-0.01^\circ < \theta_x, \theta_y < +0.01^\circ$

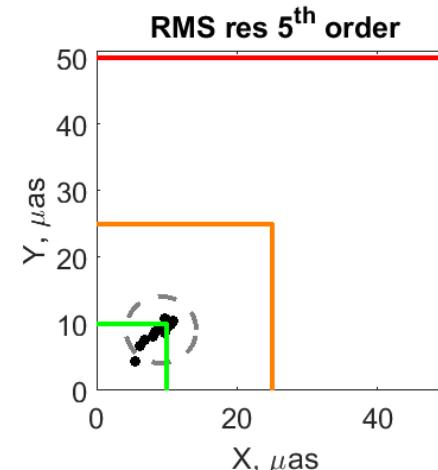
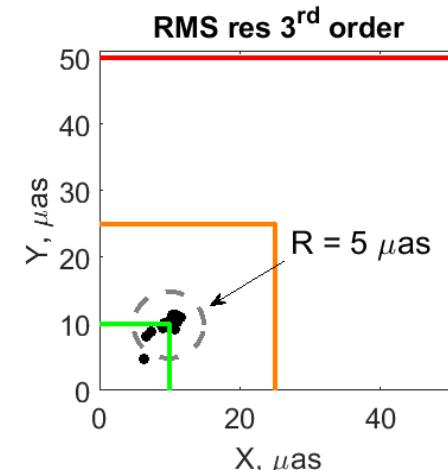
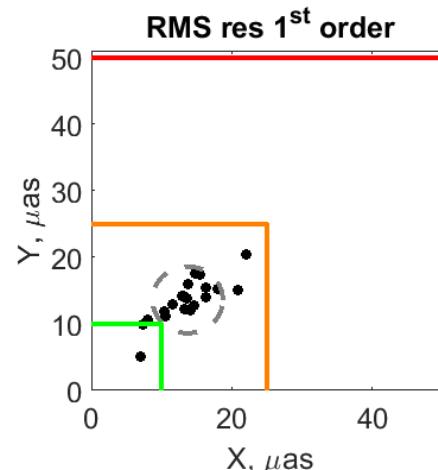
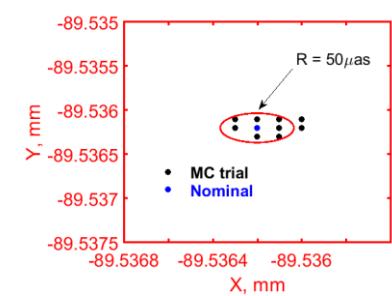
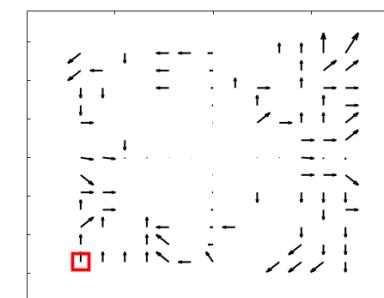
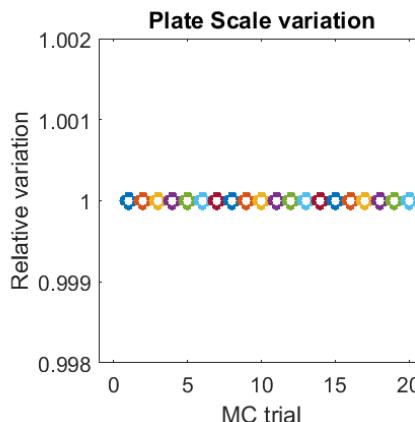
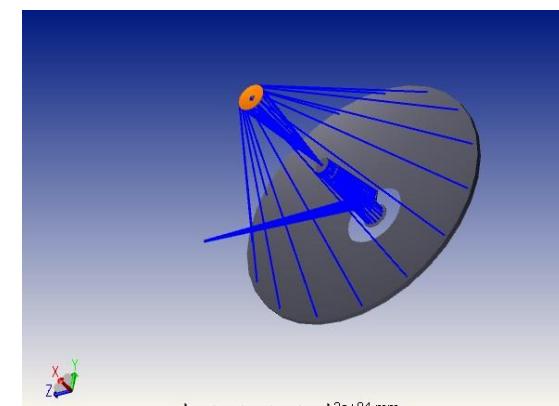
(Mueller, 2014 - Cayrel, 2012)



M2 Tolerances

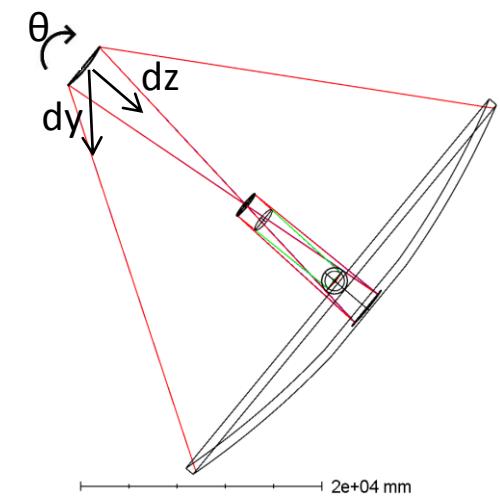
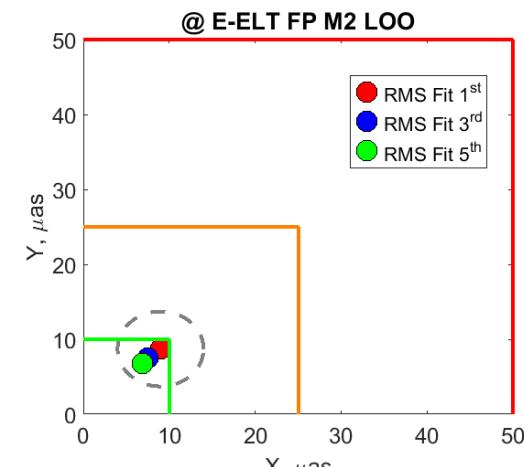
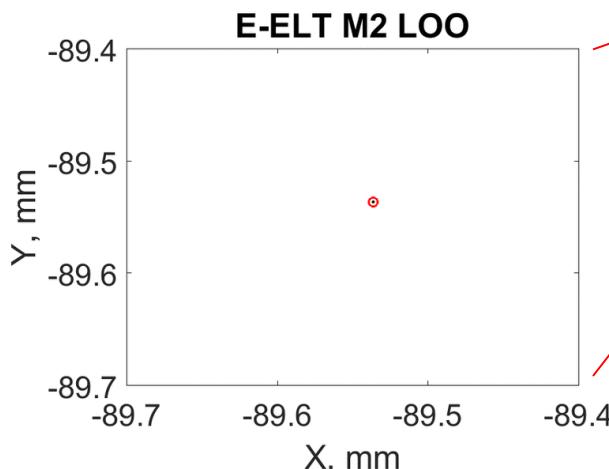
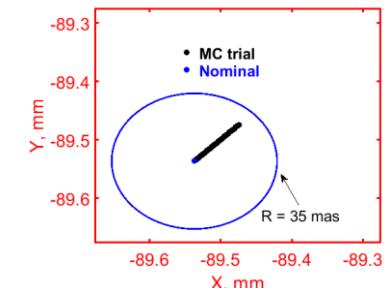
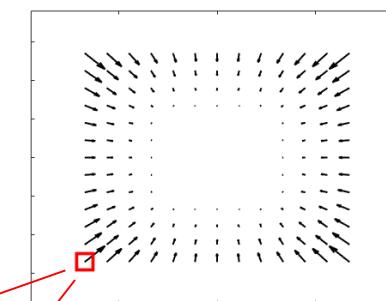
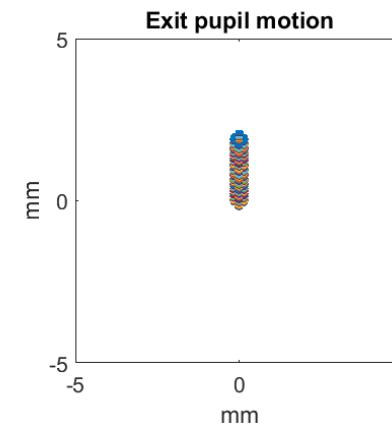
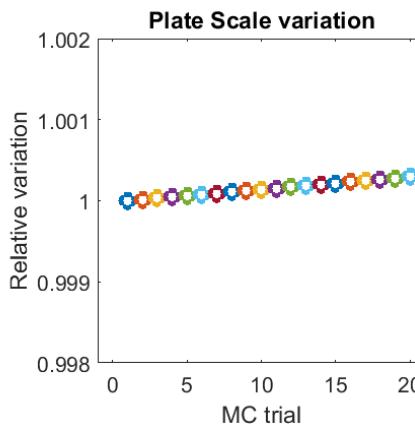
$-0.1 \text{ mm} < dx, dy < +0.1 \text{ mm} \rightarrow dz = 0$

$-0.01^\circ < \theta_x, \theta_y < +0.01^\circ$



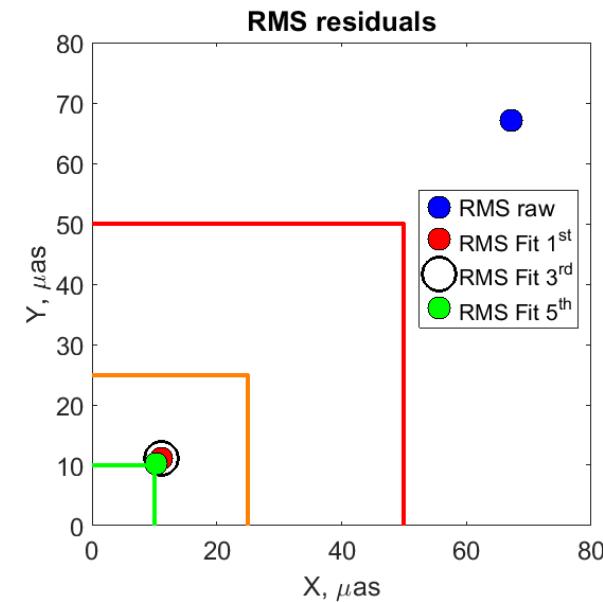
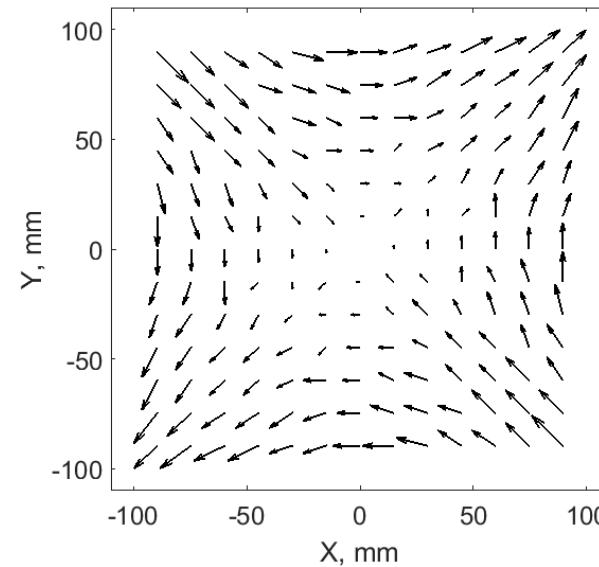
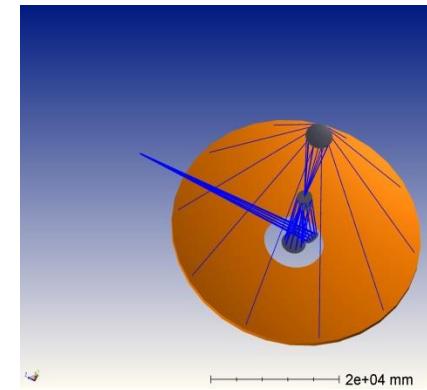
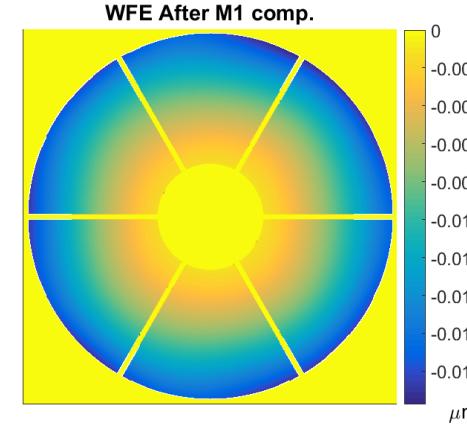
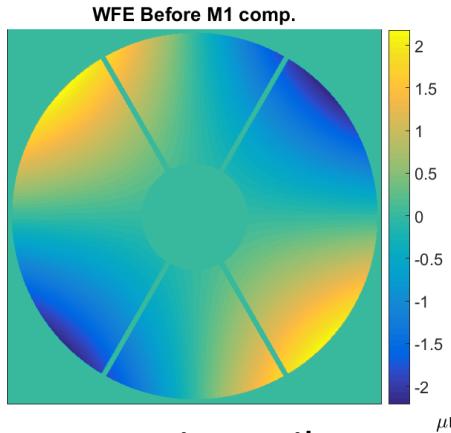
M2 Low Order Optimization

$dy, dz = 0 \rightarrow 100 \mu\text{m}$
 $\theta = 0 \rightarrow 0.01^\circ$ (Mueller, 2014)



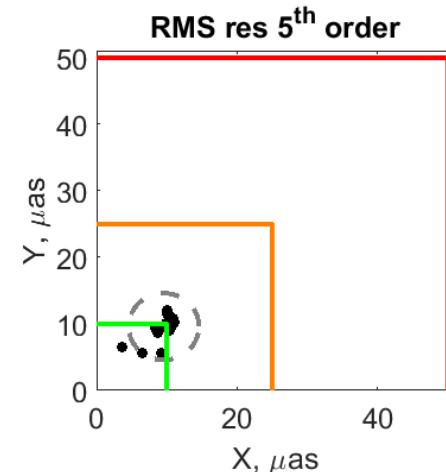
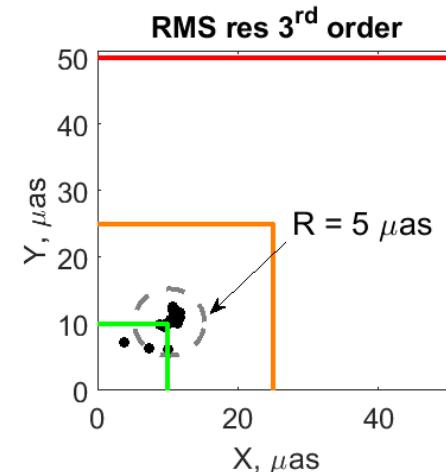
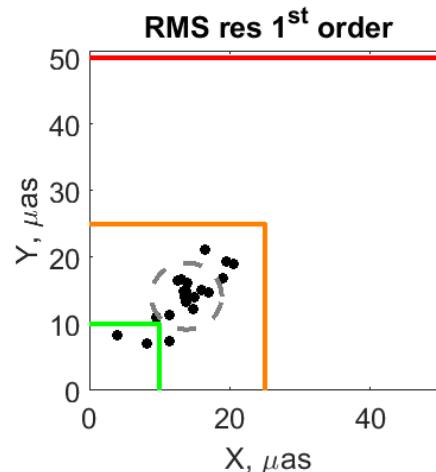
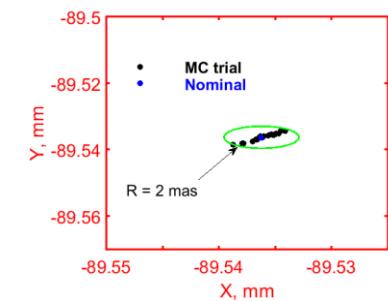
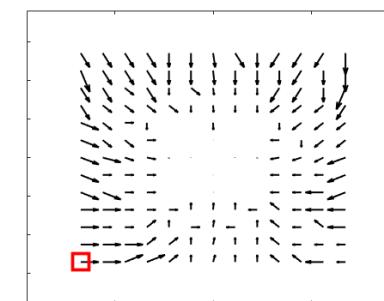
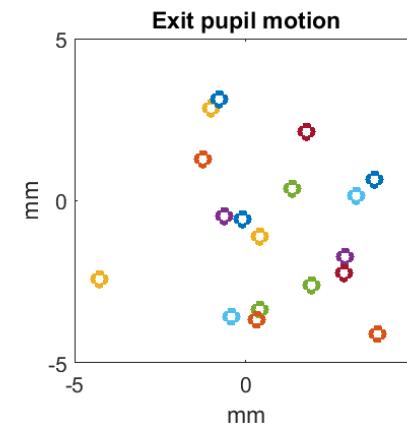
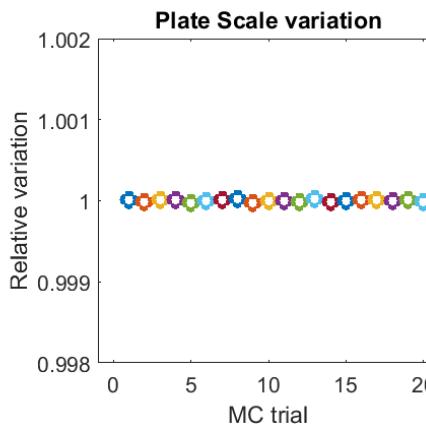
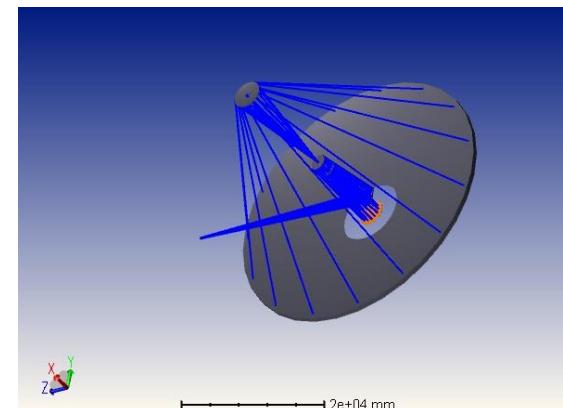
M2 shape aberrations

RMS = 506 nm astigmatism on M2 (Mueller, 2014)
M1 phasing compensation of M2 deformation



M3 Tolerances

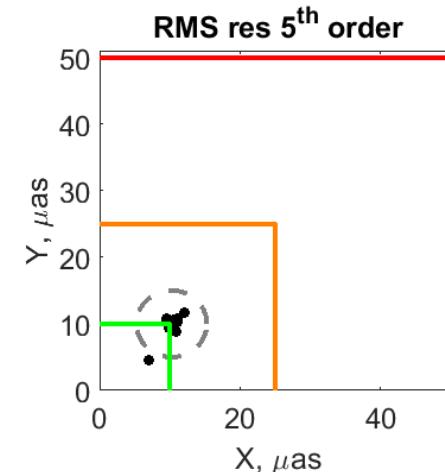
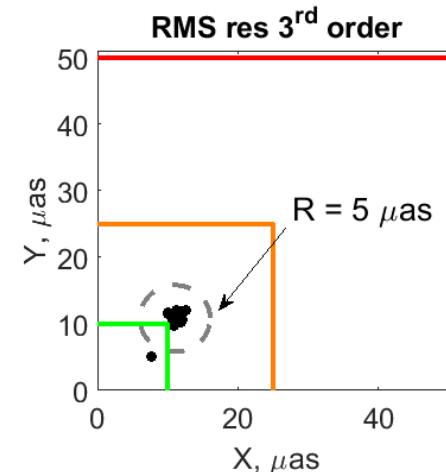
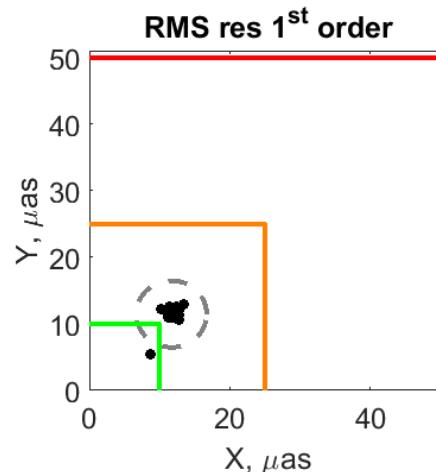
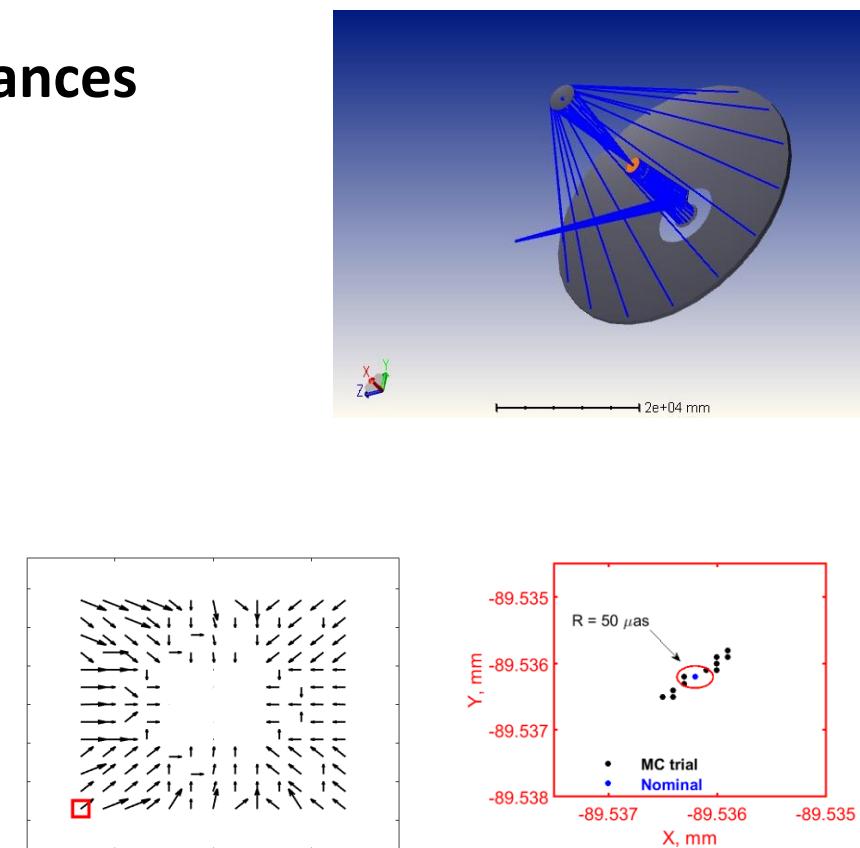
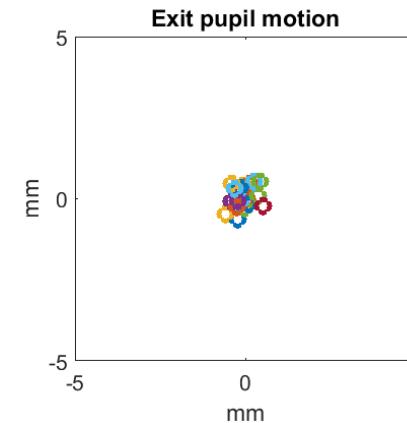
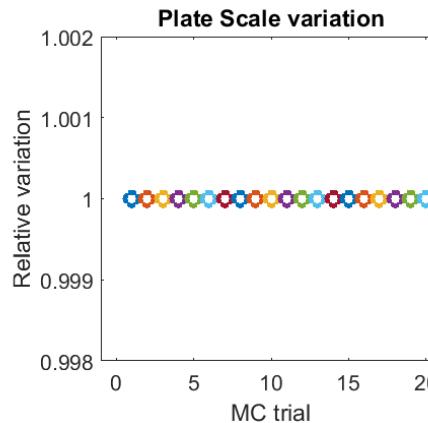
$-0.1 \text{ mm} < dx, dy, dz < +0.1 \text{ mm}$
 $-0.01^\circ < \theta_x, \theta_y < +0.01^\circ$ (Cayrel, 2012)



M4 Tolerances

$-0.1 \text{ mm} < dx, dy, dz < +0.1 \text{ mm}$

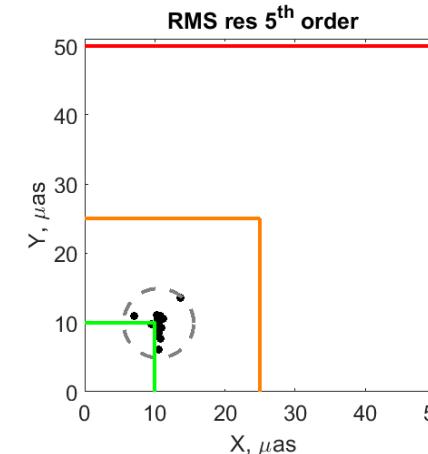
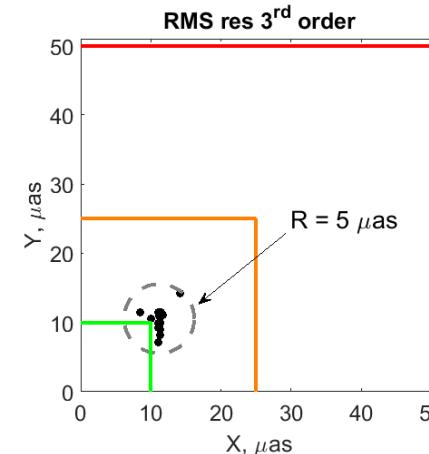
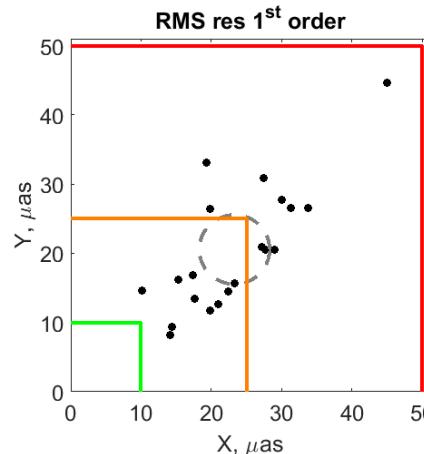
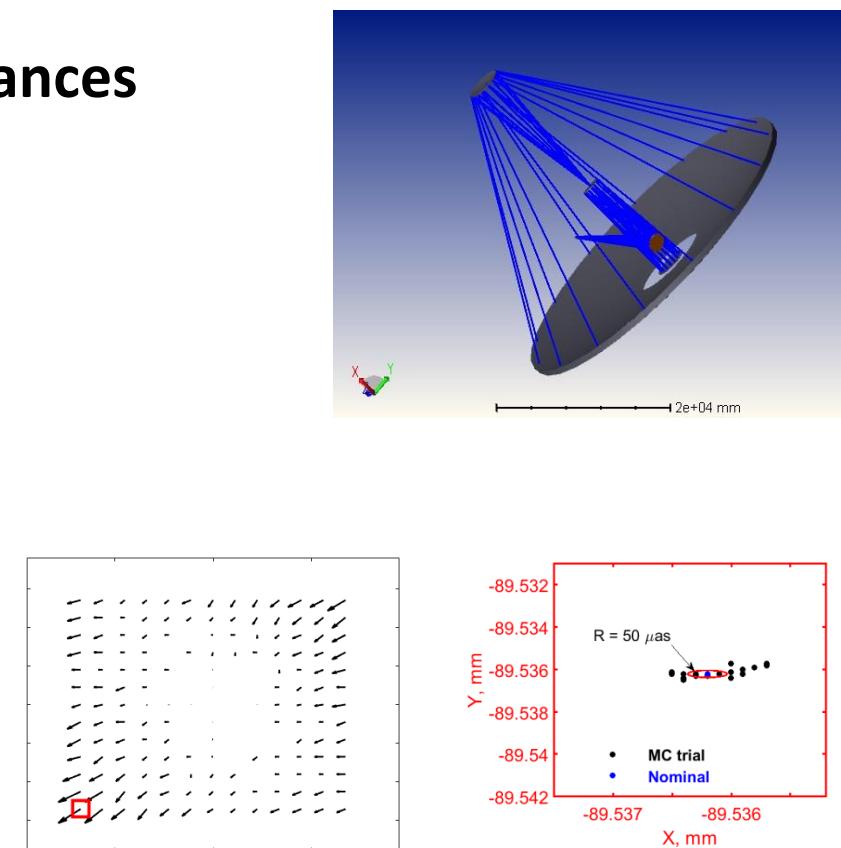
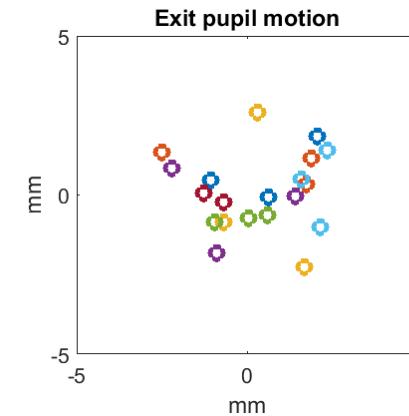
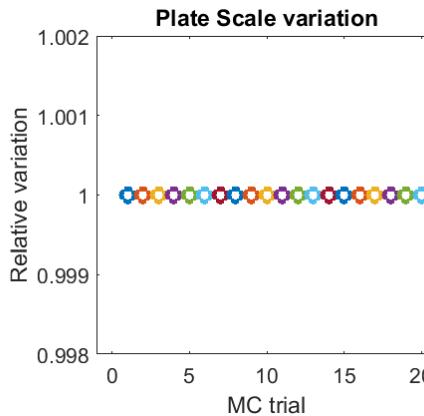
$-0.01^\circ < \theta_x, \theta_y < +0.01^\circ$



M5 Tolerances

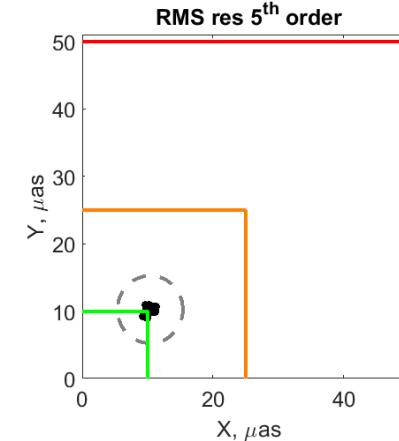
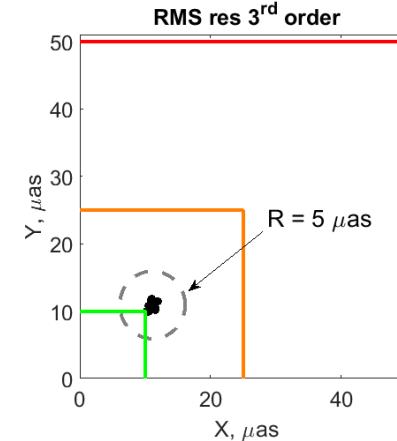
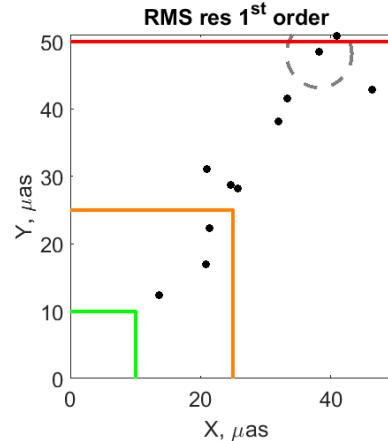
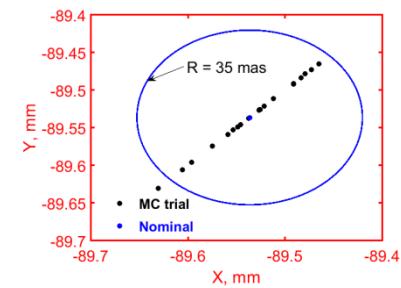
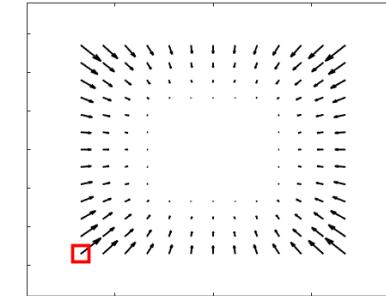
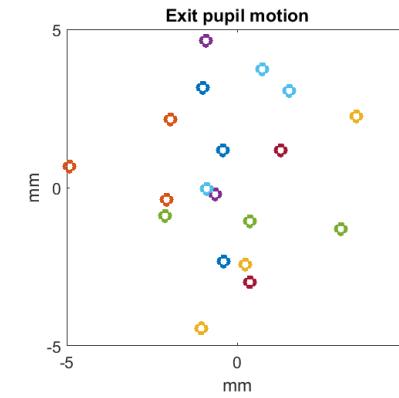
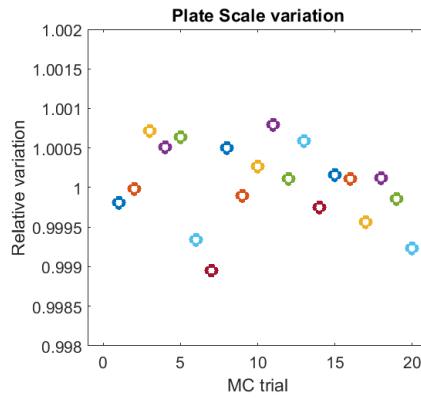
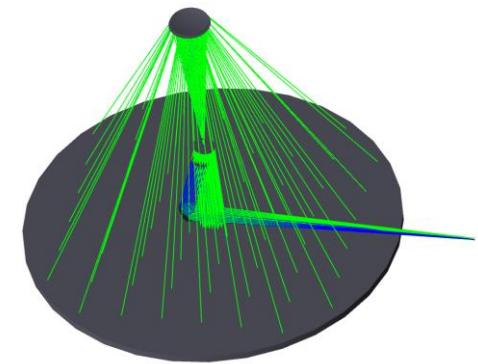
$-0.1 \text{ mm} < dx, dy, dz < +0.1 \text{ mm}$

$-0.01^\circ < \theta_x, \theta_y < +0.01^\circ$



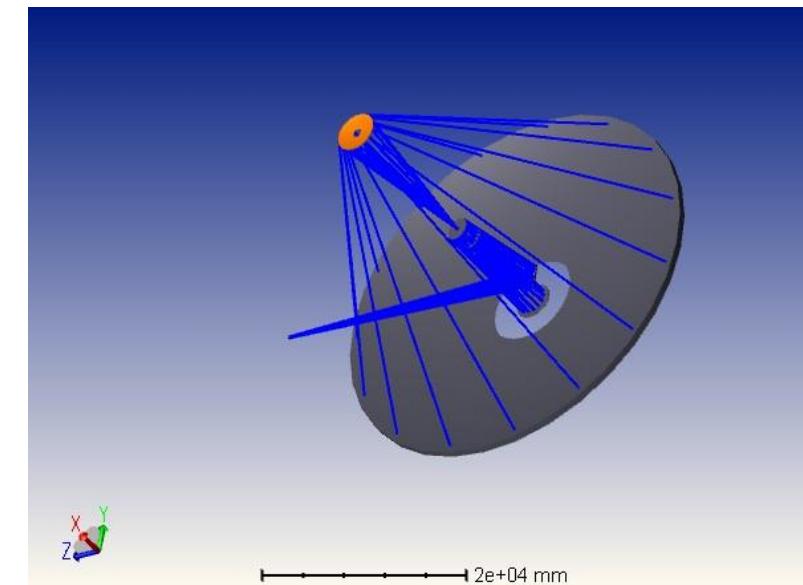
E-ELT Tolerances

Combined tolerances on M2, M3, M4 & M5



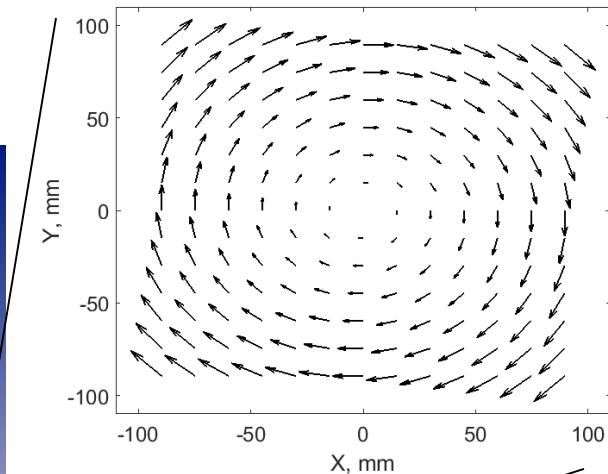
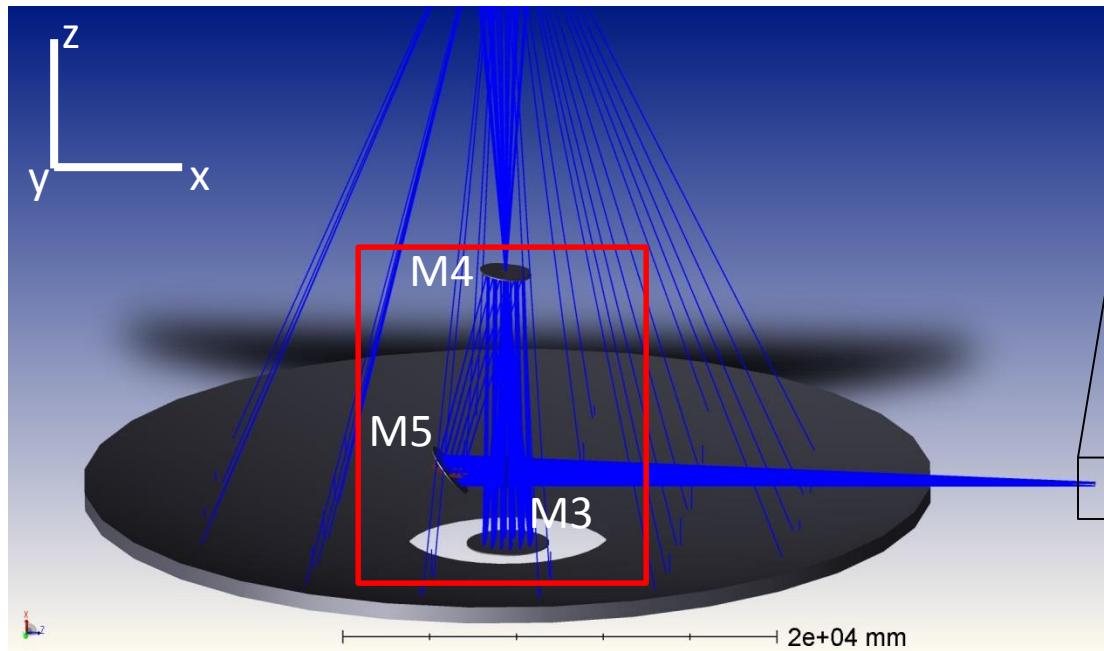
E-ELT Tolerances

- After 1st & 3rd order polynomial fit the astrometry residuals are **10-20 μ as**
- 5th order polynomial fit -> no significant improvement
- 1st order distortions are dominated by plate scale variations
- The worst offender is **M2 axial drift**
- The telescope distortions are calibrated **on sky**



M3-M4-M5 Field Rotation

The system M3-M4-M5 -> k-mirror



Field stabilization M5 -> 100 Hz
 (Casalta, 2010)

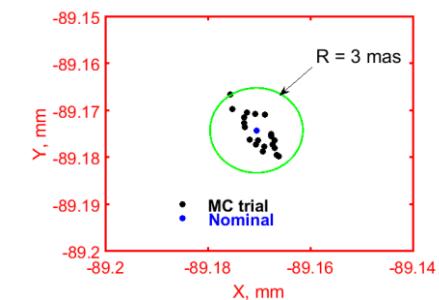
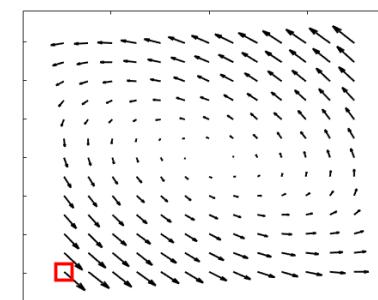
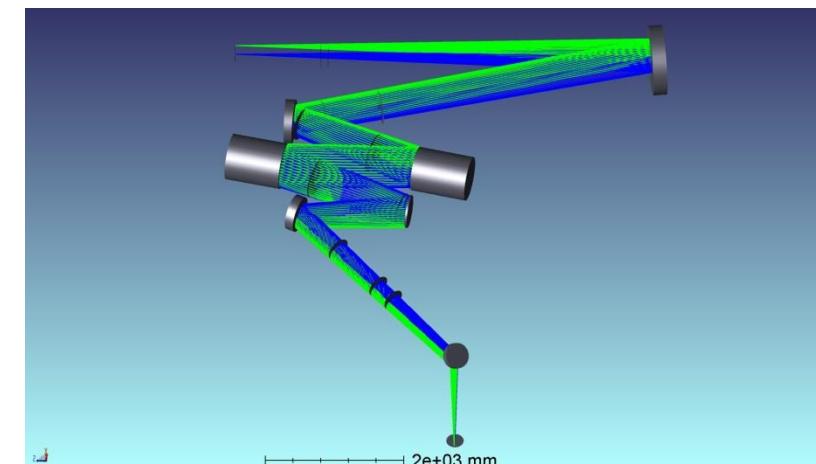
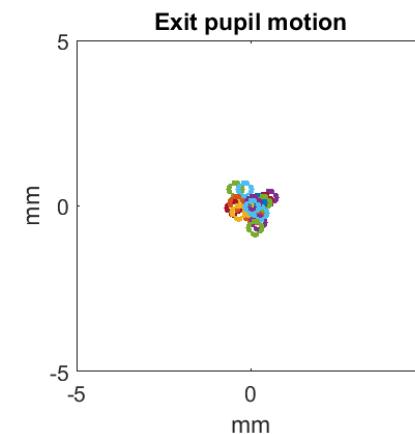
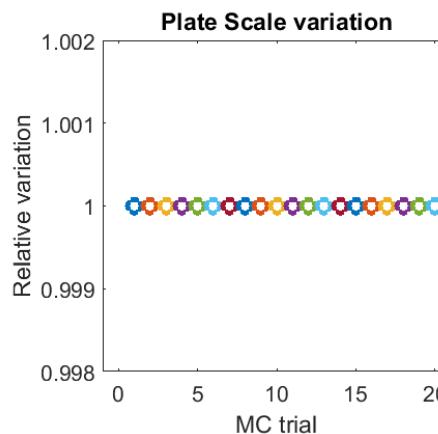
- Seeing 1" M5 -> FR jitter 14"
- PSF shift FoV(30") -> 2 mas

Tilt	M3	M4	M5
$\theta_x = 0.01^\circ$	-	3"	42"
$\theta_y = 0.01^\circ$	-	-	-
$\theta_z = 0.01^\circ$	-	10"	24"

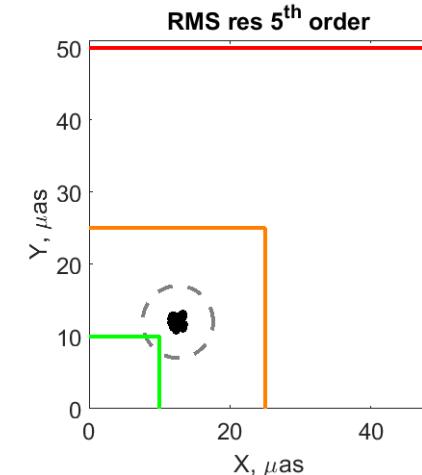
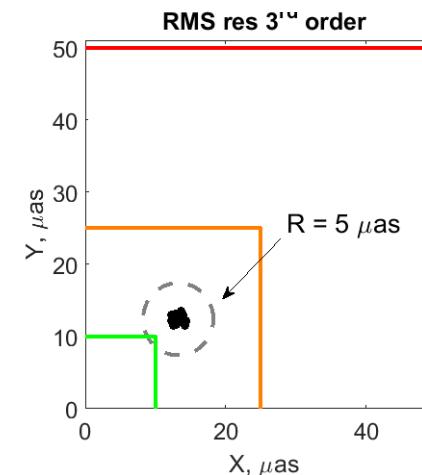
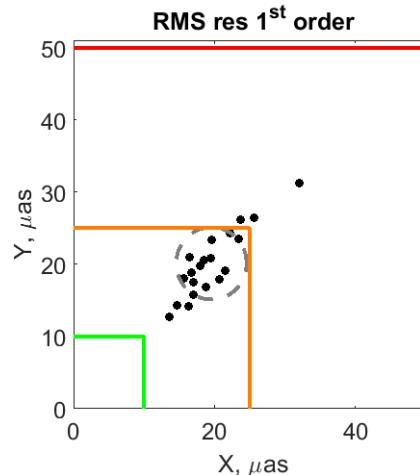
Field	H , mas	K, mas
On axis	7	10
Off axis	10	13

MAORY Tolerances

$-50 \mu\text{m} < dx, dy, dz < +50 \mu\text{m} + \Delta\text{Bench}(dT/h = 1^\circ\text{C})$
 $-0.001^\circ < \theta_x, \theta_y < +0.001^\circ$



- DMs nominal sag from prescription

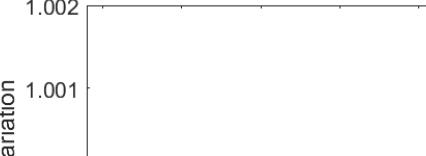


MAORY Tolerances

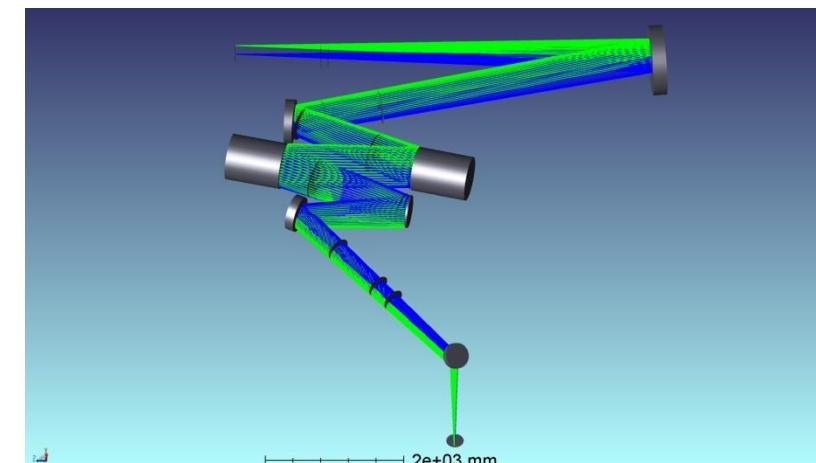
$-50 \mu\text{m} < dx, dy, dz < +50 \mu\text{m} + \Delta\text{Bench}(dT/h = 1^\circ\text{C})$

$-0.001^\circ < \theta_x, \theta_y < +0.001^\circ$

Plate Scale variation



Exit pupil motion

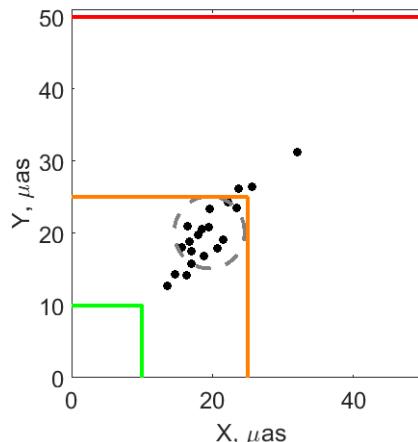


Mauro Patti's Poster session 1 [P1012]

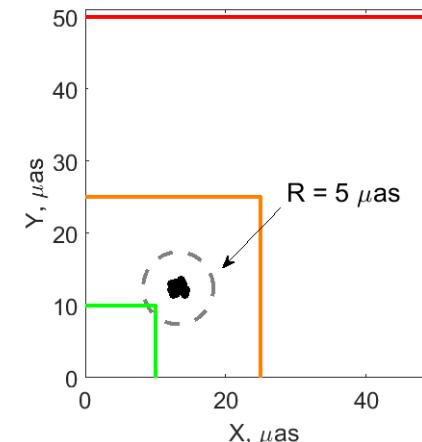
'Exploring MAORY performances through tolerance analysis'



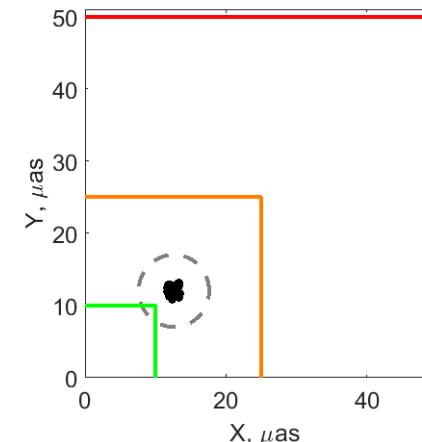
RMS res 1st order



RMS res 3rd order

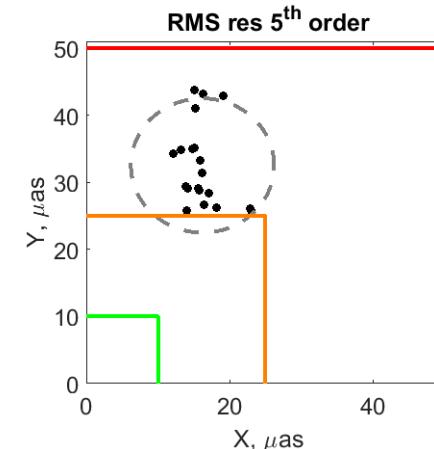
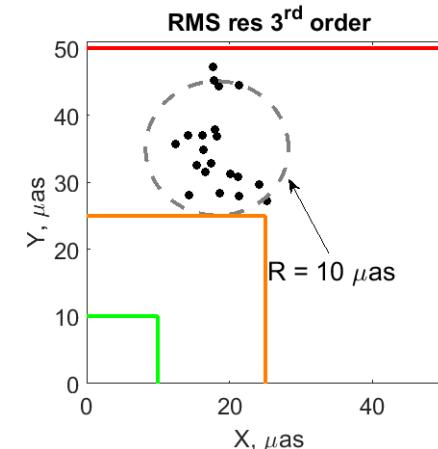
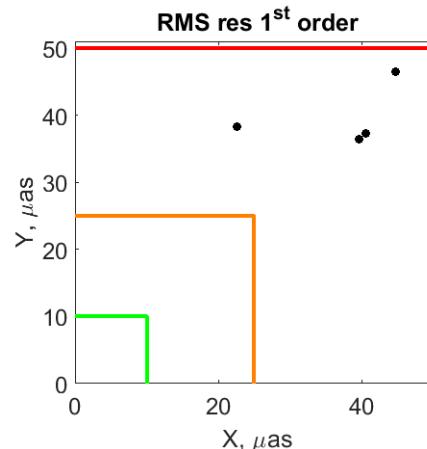
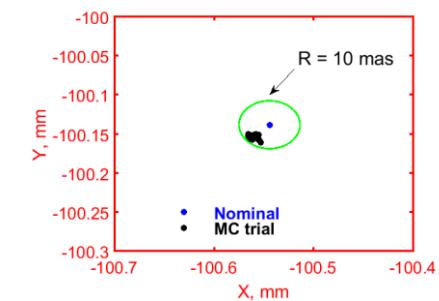
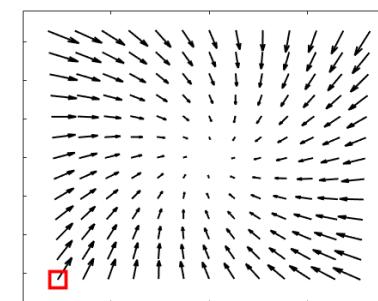
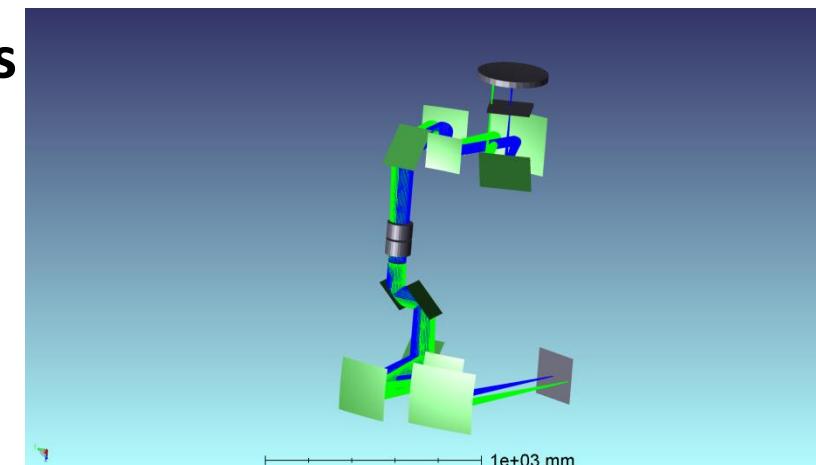
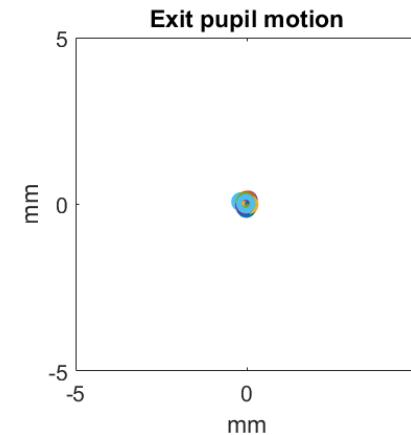
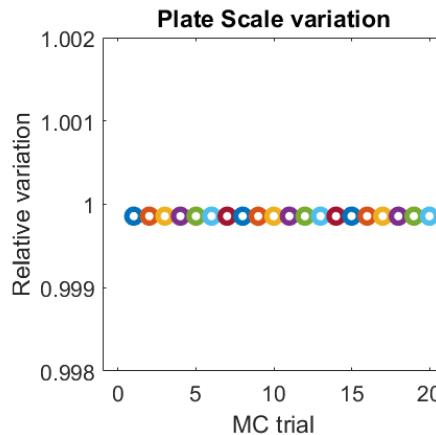


RMS res 5th order



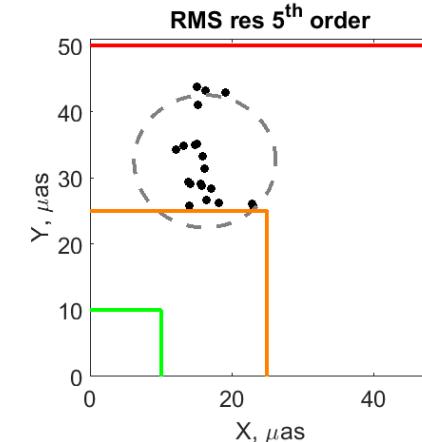
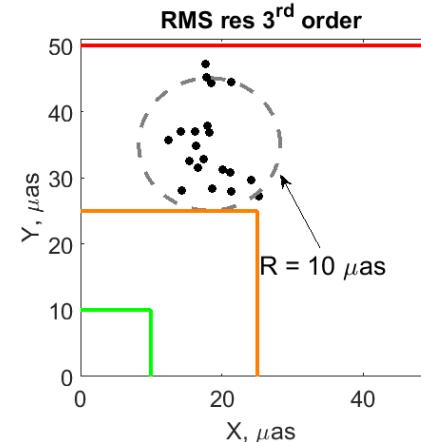
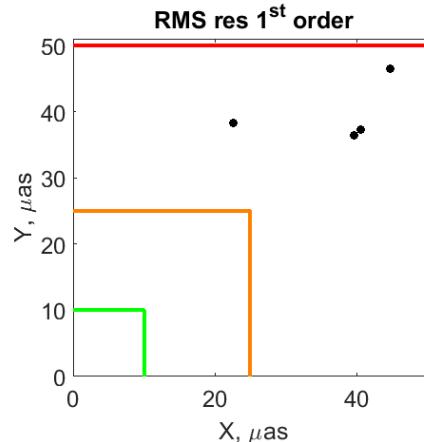
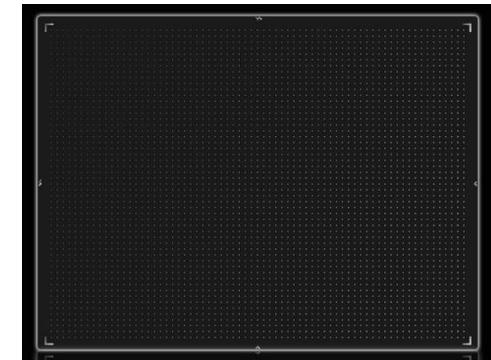
MICADO Tolerances

$-0.5 \mu\text{m} < dx, dy, dz < +0.5 \mu\text{m}$
 $-0.001^\circ < \theta_x, \theta_y < +0.001^\circ$ (Scheiding, 2010)

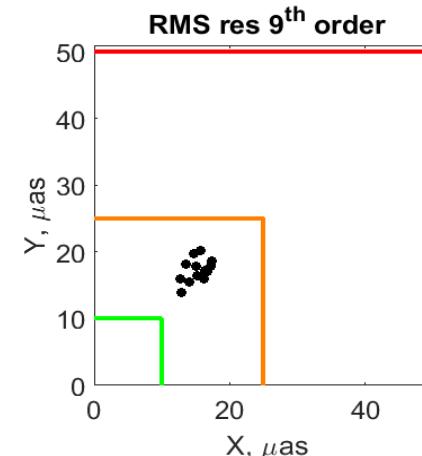
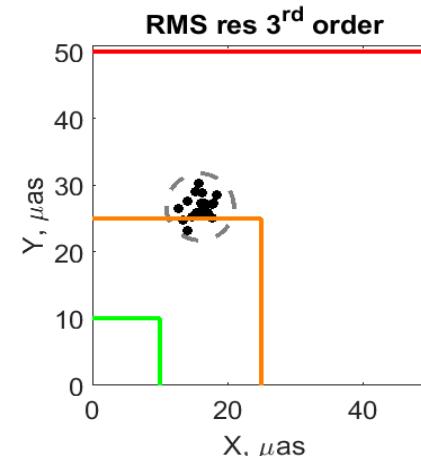
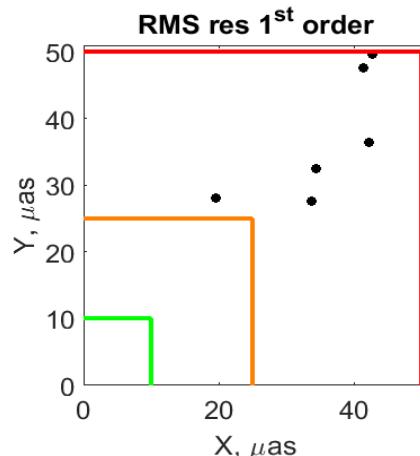


MICADO Tolerances

MICADO and MAORY optical distortions
Calibrated with astrometric calibration masks



144 points



900 points

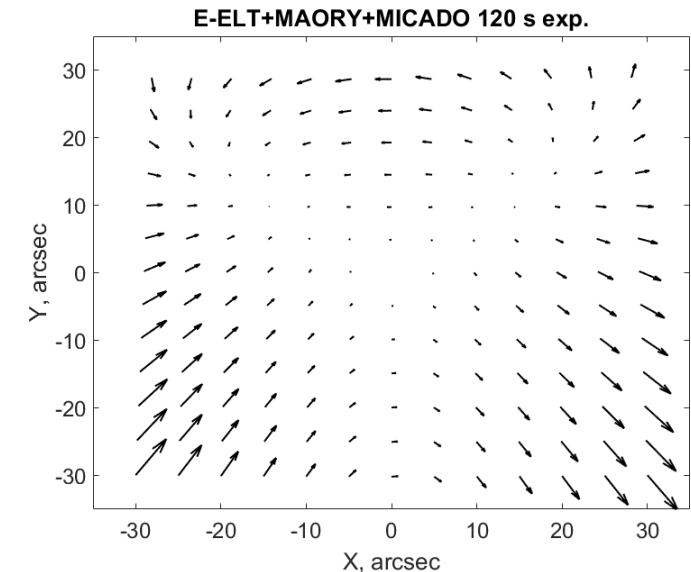
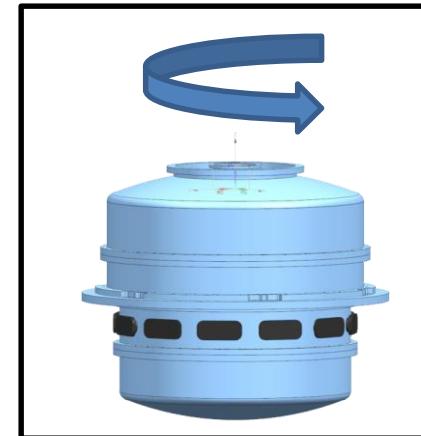
Distortion(Derotation)

Derotation MAORY-MICADO

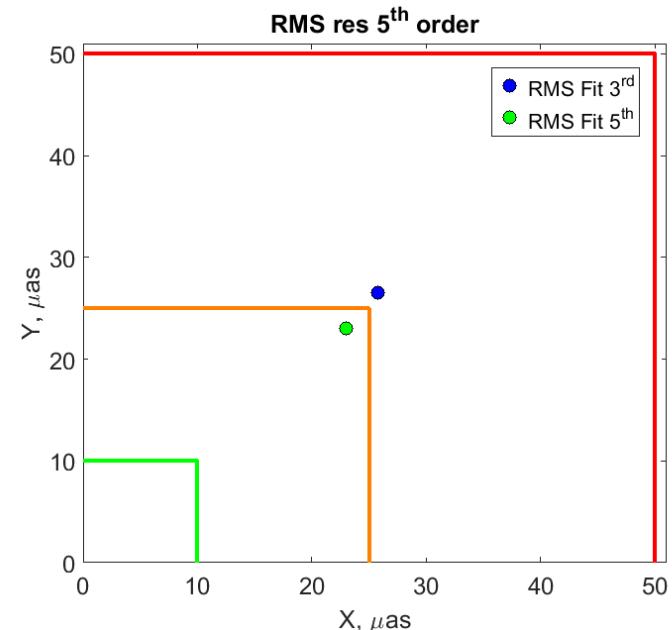
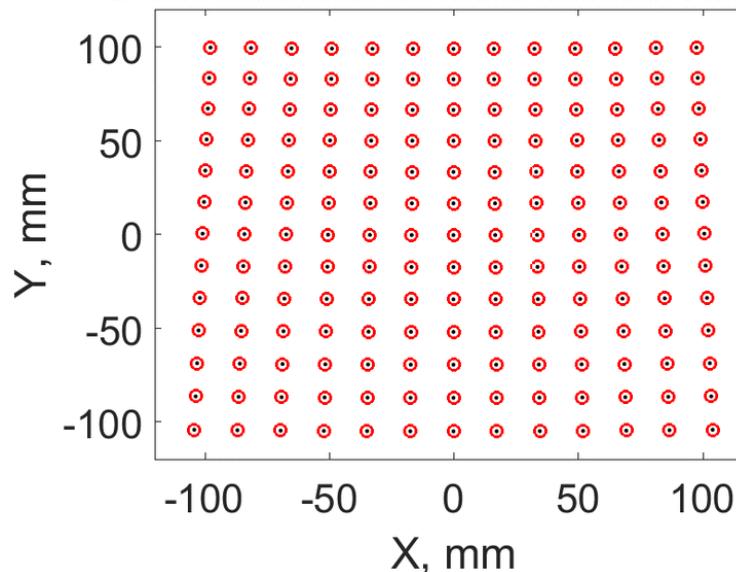
Max speed 79"/s

Max exposure 120 s

Diff. Derotation <= 2.6°



E-ELT+MAORY+MICADO Full Derotation



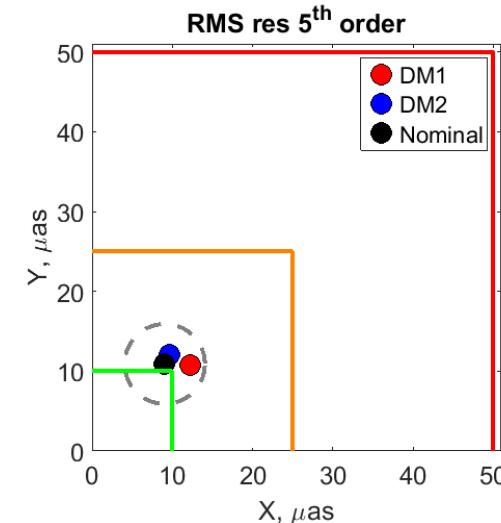
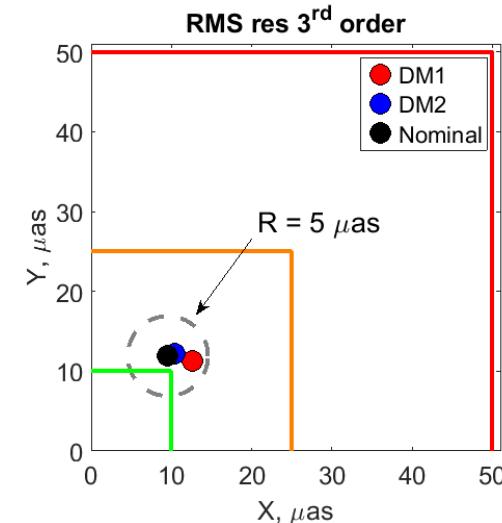
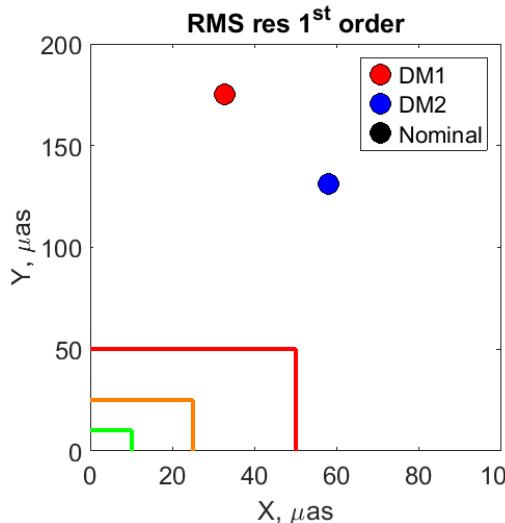
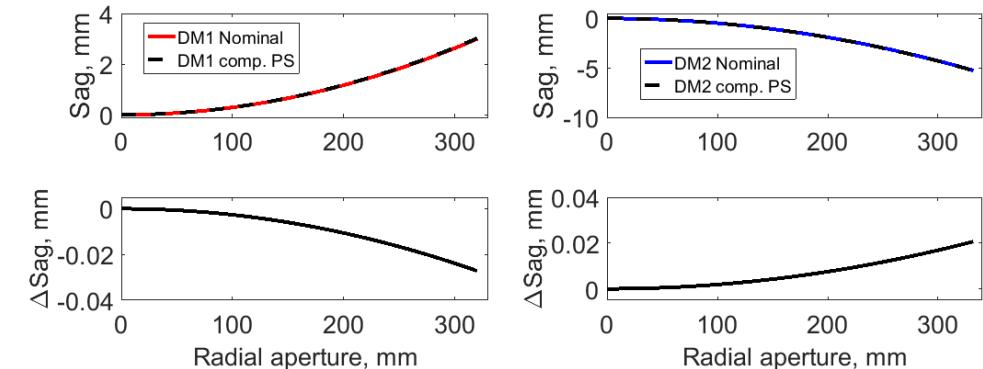
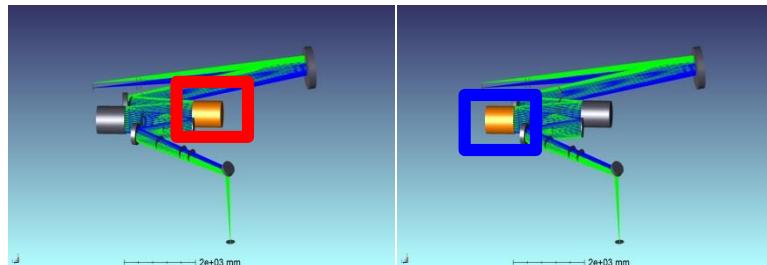
E-ELT PS compensation with MAORY DMs

M2 $\Delta z = 1 \text{ mm} \rightarrow \Delta \text{Plate Scale} = 1\%$

Restore PS with MAORY DMs

Guiding windows on MICADO detector

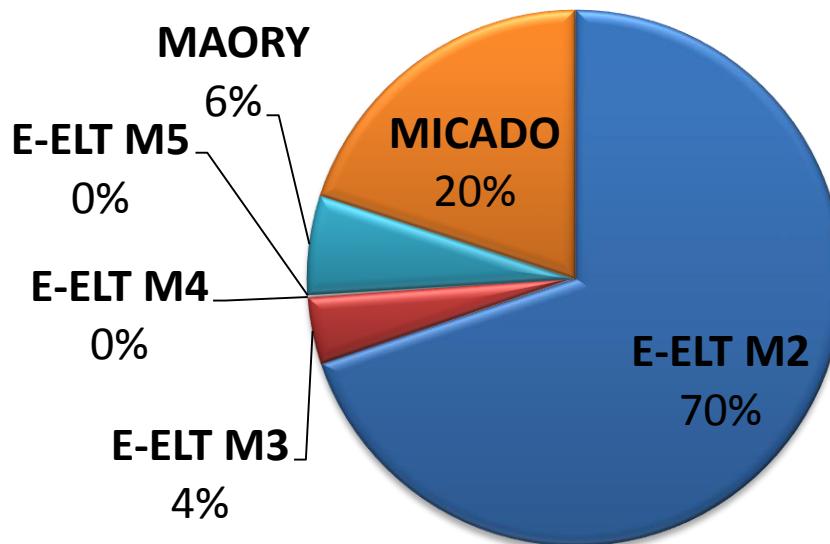
Stroke required 20-30 μm



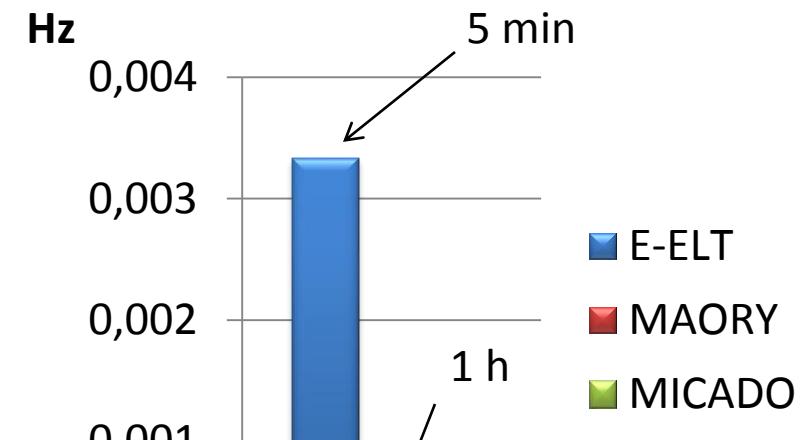
Astrometric Error Budget summary

- Mirror misalignment/positioning errors
- Thermo-mechanical drifts
- Dynamical effect (LOO)

Distortion intrinsic+tolerances



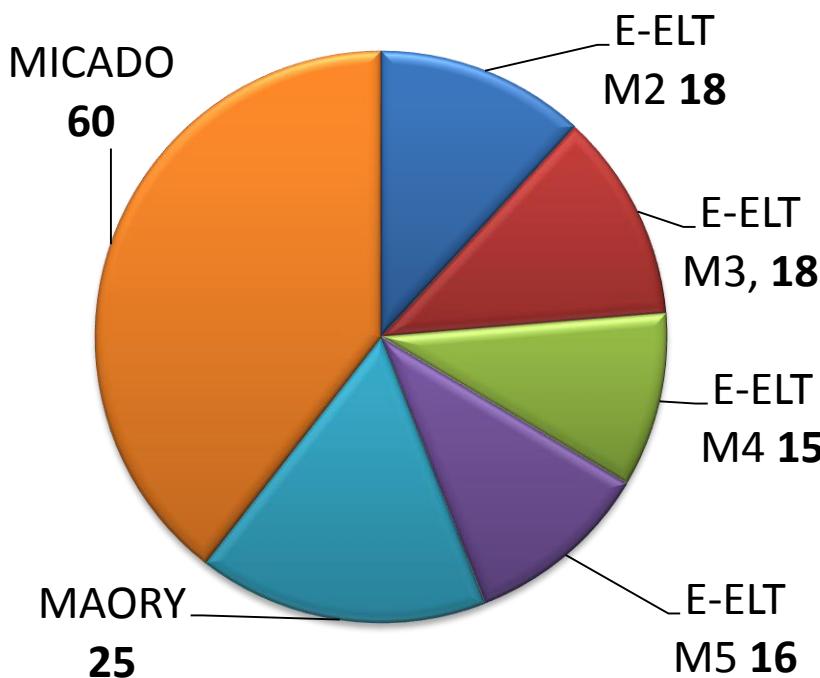
Timescales



NIRSPEC TMA ≈ 0.4 h (Yi, 2015)

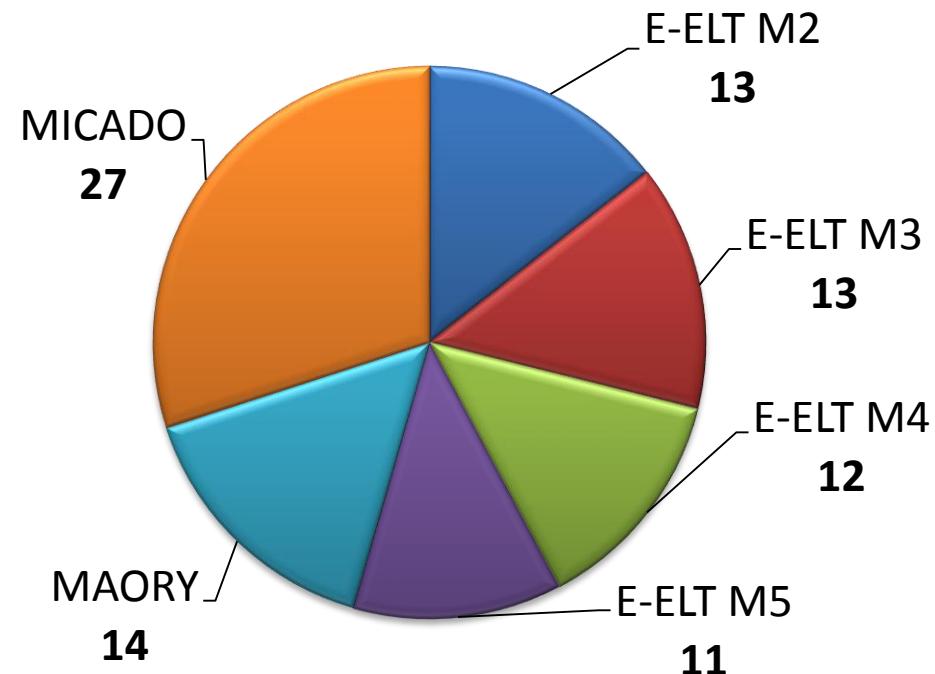
Astrometric Error Budget summary

RMS residuals post 1st fit



[μas]

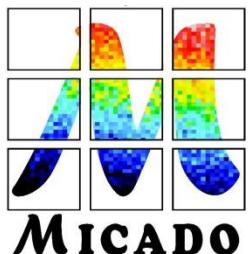
RMS residuals post 3rd fit



[μas]

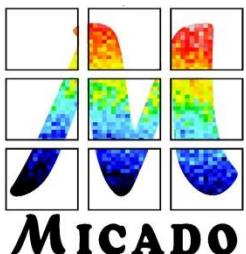
Conclusions & future perspectives

- E-ELT dominant distortion -> PS change, limit on exposure time



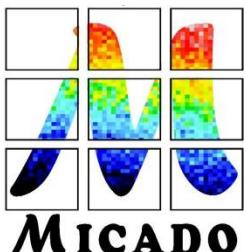
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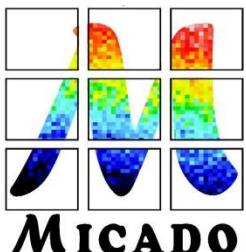
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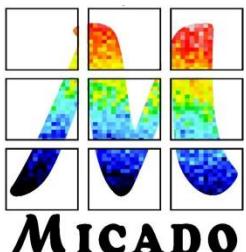
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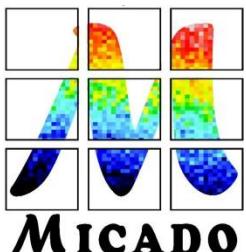
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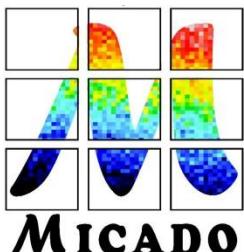
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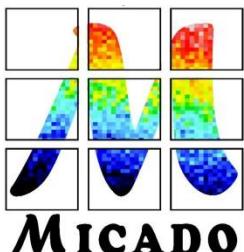


Conclusions & future perspectives

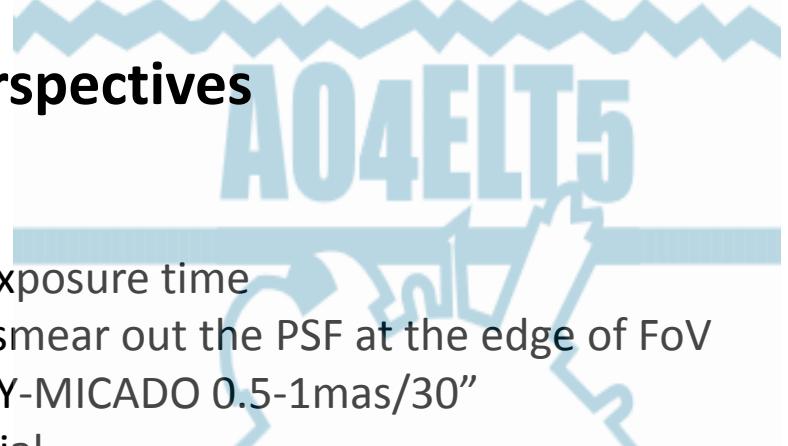
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Possible strategies:

- Smaller FoV

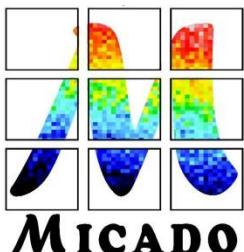


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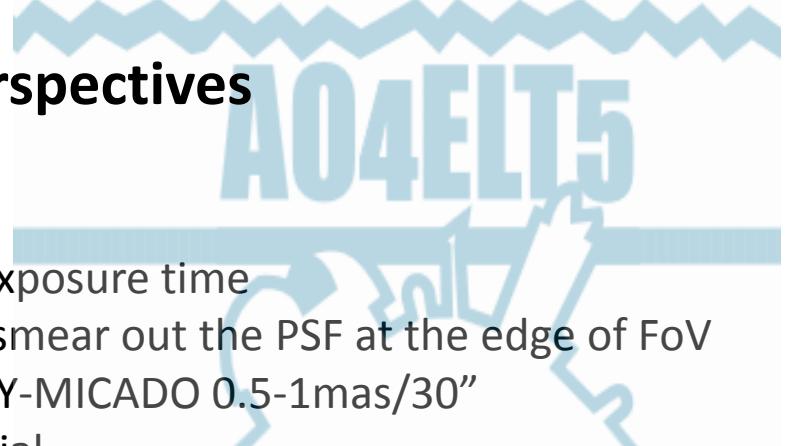
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Possible strategies:

- Smaller FoV
- Plate Scale control beyond E-ELT collimation control

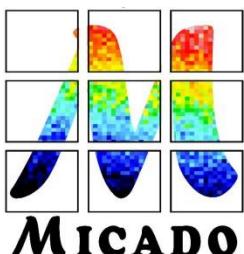


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Possible strategies:

- Smaller FoV
- Plate Scale control beyond E-ELT collimation control
- Integrate faster, penalty -> higher RON

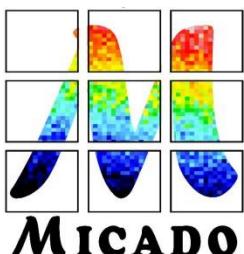


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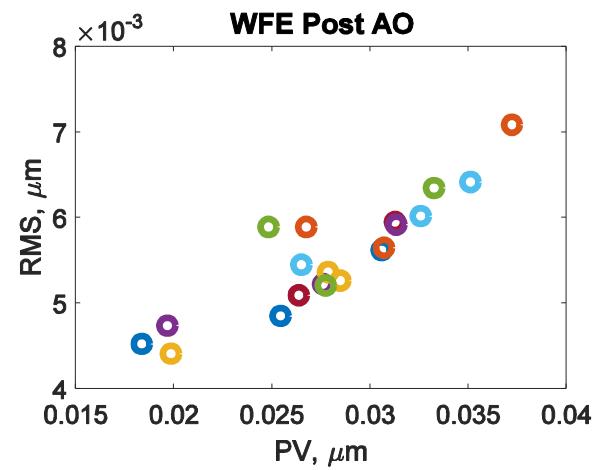
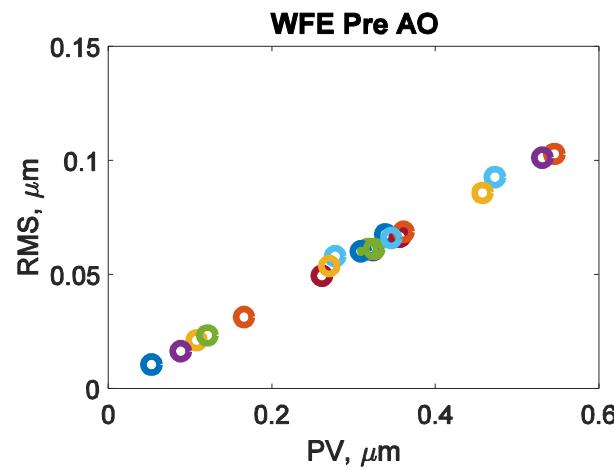
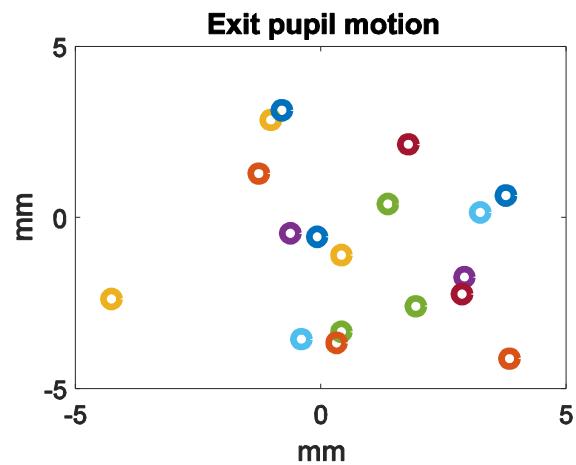
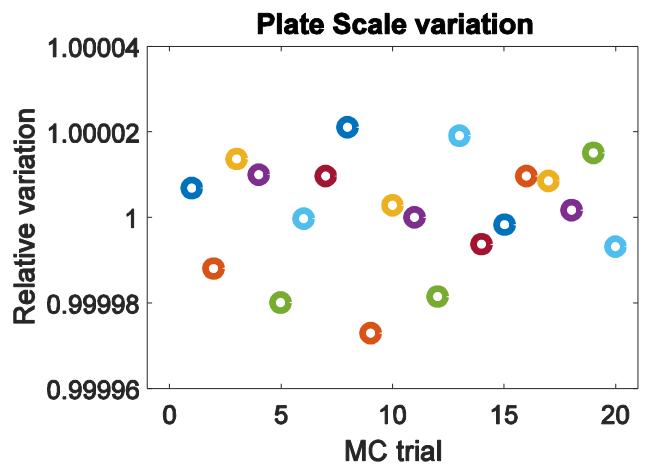
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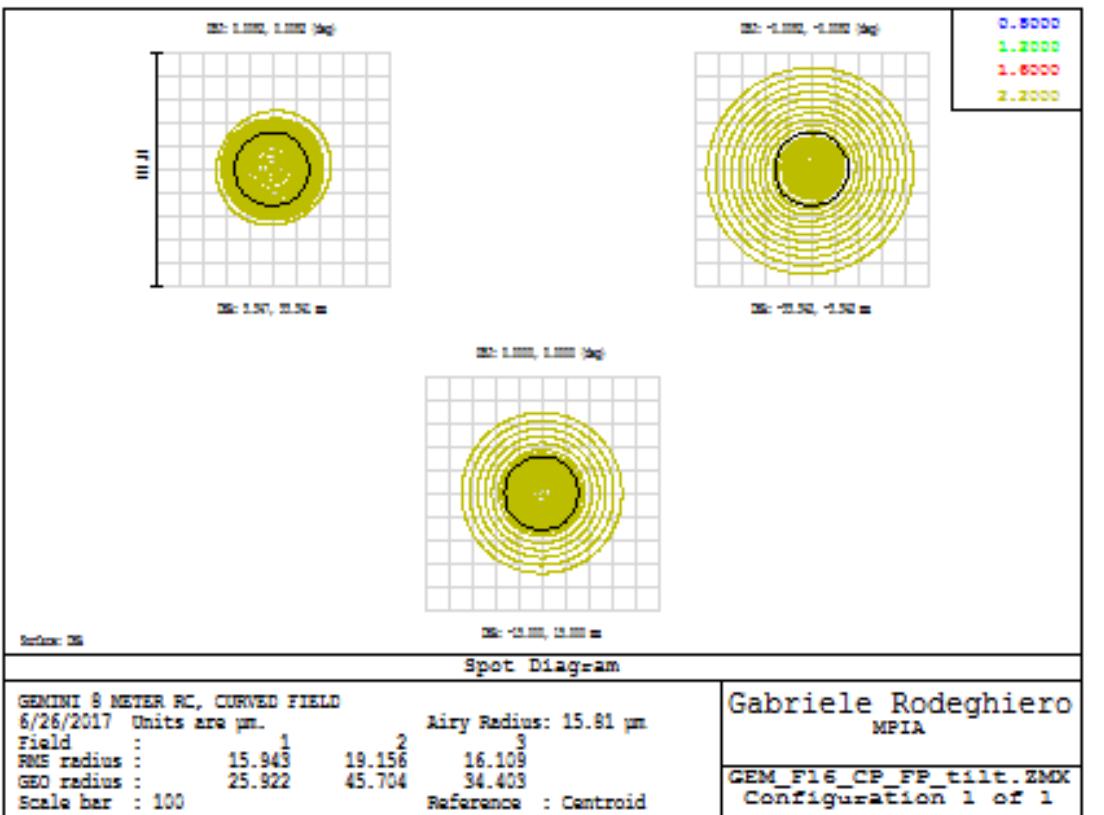
- Smaller FoV
- Plate Scale control beyond E-ELT collimation control
- Integrate faster, penalty -> higher RON
- Try to fit the distortion drifts over exposure timescale (PS, FR drifts)



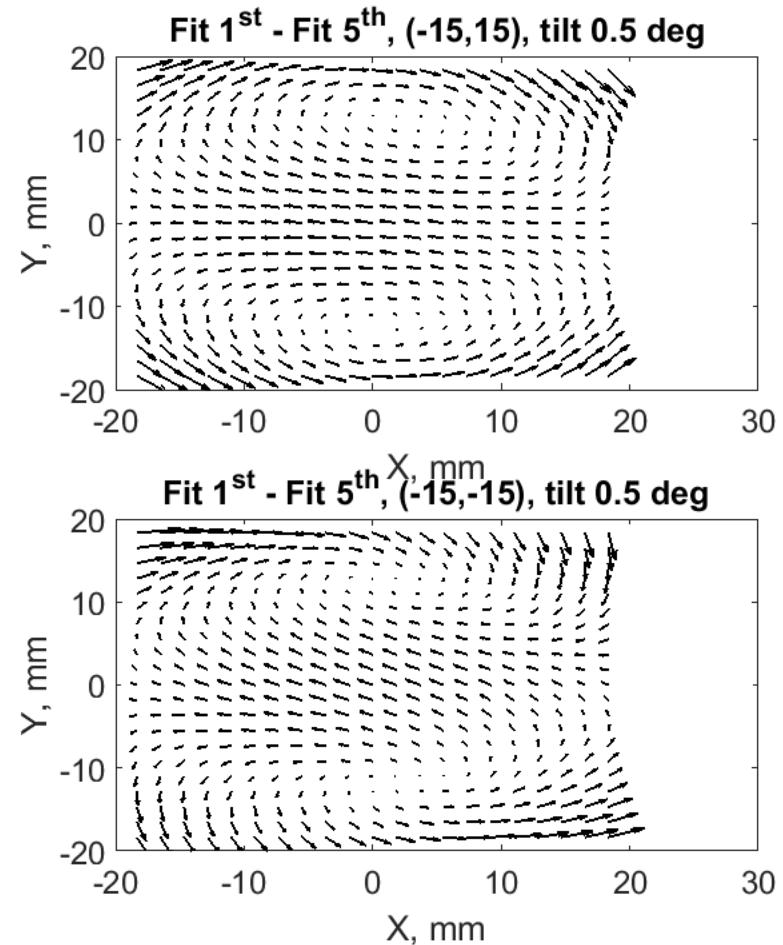
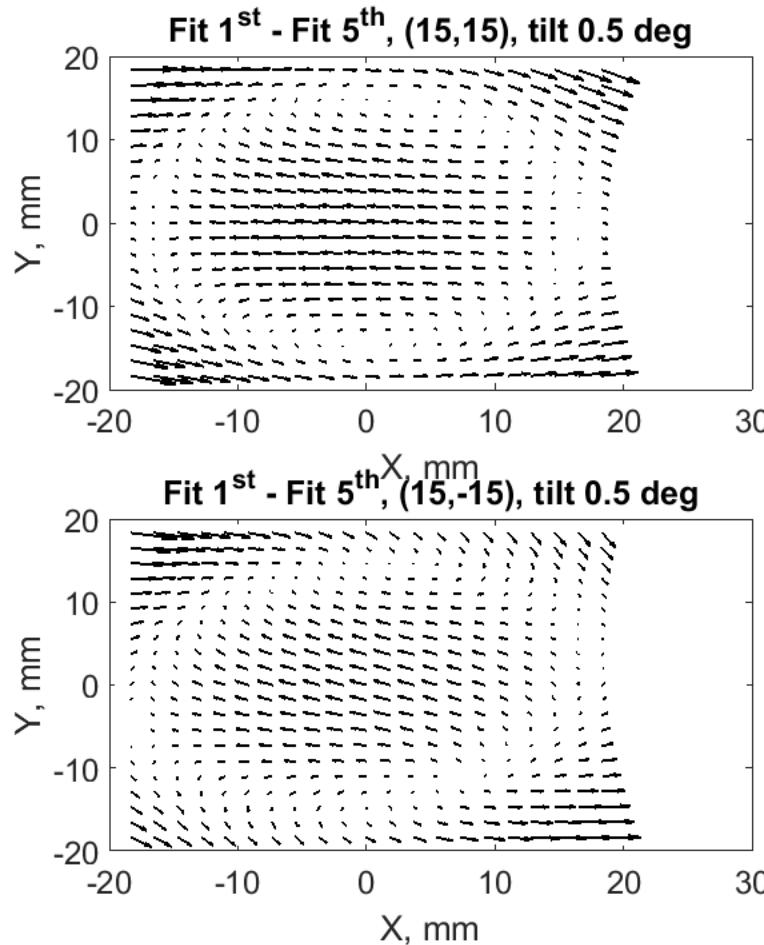
Backup slides



Backup slides



Backup slides



Backup slides

